

Geometry of Neuron manifolds

$\mu: \Theta \times X \rightarrow Y$ polynomial (in both $\theta \in \Theta$ & $x \in X$)

$$\begin{array}{ccc} \Theta & \longrightarrow & \mathcal{M} \\ \theta & \longmapsto & \mu(\theta, \cdot) \end{array}$$

What kind of object is \mathcal{M} ?

Geometry of Neuron manifolds

$\mu: \Theta \times X \rightarrow Y$ polynomial (in both $\theta \in \Theta$ & $x \in X$)

$$\begin{array}{ccc} \Theta & \longrightarrow & \mathcal{M} \\ \theta & \longmapsto & \mu(\theta, \cdot) \end{array}$$

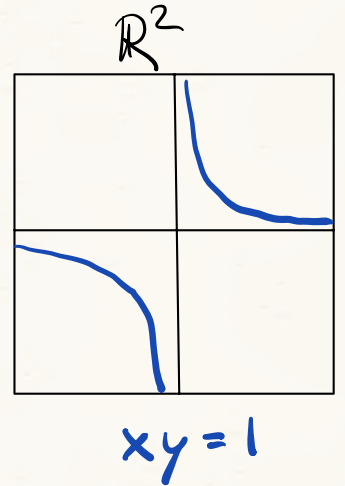
What kind of object is \mathcal{M} ?

A **semialgebraic** set!

describable by
polynomial equations
& inequalities

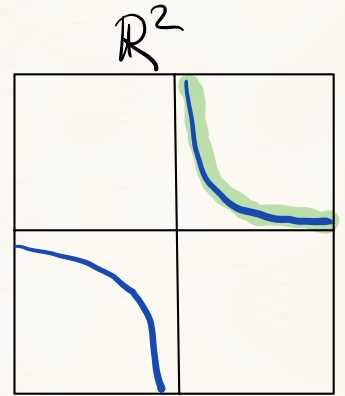
(Semi)Algebraic Sets

An **algebraic set / algebraic variety** in \mathbb{R}^n is a solution set of a system of polynomial equations in $\mathbb{R}[x_1, \dots, x_n]$.



(Semi)Algebraic Sets

An **algebraic set / algebraic variety** in \mathbb{R}^n is a solution set of a system of polynomial equations in $\mathbb{R}[x_1, \dots, x_n]$.



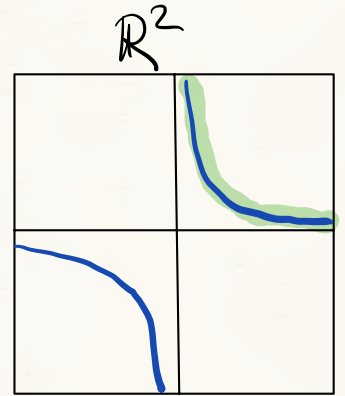
A **basic semialgebraic set** in \mathbb{R}^n is a solution set of a system of polynomial equations and polynomial inequalities in $\mathbb{R}[x_1, \dots, x_n]$.

$$xy=1$$

$$x>0$$

(Semi) Algebraic Sets

An **algebraic set / algebraic variety** in \mathbb{R}^n is a solution set of a system of polynomial equations in $\mathbb{R}[x_1, \dots, x_n]$.

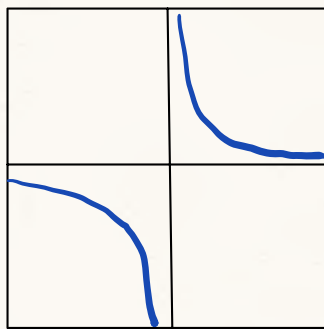


$$xy = 1$$

$x > 0$

A **basic semialgebraic set** in \mathbb{R}^n is a solution set of a system of polynomial equations and polynomial inequalities in $\mathbb{R}[x_1, \dots, x_n]$.

A **semialgebraic set** is a finite union of basic semialgebraic sets.



$$xy = 1$$

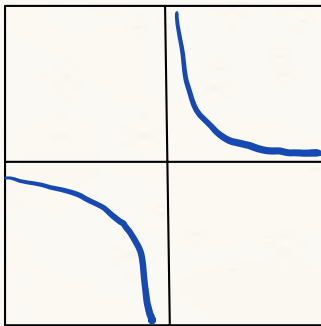
$$(x, y) \mapsto x$$

$$x < 0 \cup x > 0$$

Tarski-Sidorenberg Theorem

A morphism between algebraic varieties $\varphi: \overset{\mathbb{R}^n}{\underset{\subset}{X}} \longrightarrow \overset{\mathbb{R}^n}{\underset{\subset}{Y}}$ is a polynomial map, i.e., $\varphi = (\varphi_1, \dots, \varphi_m)$ & $\varphi_i \in \mathbb{R}[x_1, \dots, x_n]$.

→ **Thm:** $\varphi(X)$ is a semi-algebraic set.



$$xy = 1$$

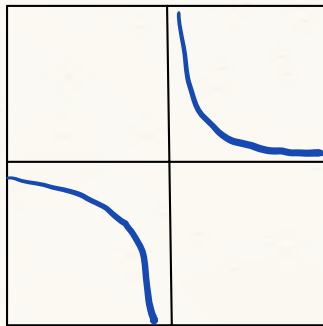
$$(x, y) \mapsto x$$

$$x < 0 \cup x > 0$$

Tarski-Sidorenberg Theorem

A morphism between algebraic varieties $\varphi: \overset{\mathbb{R}^n}{\cup} X \rightarrow \overset{\mathbb{R}^n}{\cup} Y$ is a polynomial map, i.e., $\varphi = (\varphi_1, \dots, \varphi_m)$ & $\varphi_i \in \mathbb{R}[x_1, \dots, x_n]$.

→ **Thm:** $\varphi(X)$ is a semi-algebraic set.



$$xy = 1$$

$$(x, y) \mapsto x$$

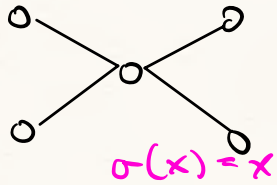
$$x < 0 \cup x > 0$$

$$\mu: \Theta \times X \rightarrow Y \quad \begin{array}{l} \text{polynomial in } x \in X \\ \& \text{ in } \theta \in \Theta \end{array}$$

- $\Rightarrow M \subseteq V$ of finite dimension
- $\Rightarrow M$ is semi-algebraic

$$\begin{array}{ccc} \Theta & \longrightarrow & \mathcal{M} \\ \theta & \longmapsto & \mu(\theta, \cdot) \end{array}$$

Linear MLPs:

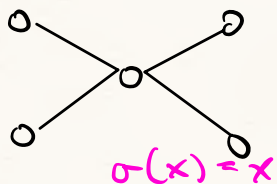


$$\begin{bmatrix} c \\ d \end{bmatrix} \begin{bmatrix} a & b \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\Rightarrow \mathcal{M} = \{ W \in \mathbb{R}^{2 \times 2} \mid \text{rk}(W) \leq 1 \}$$

Is \mathcal{M} a variety or just a semialgebraic set?

Linear MLPs:



$$\begin{bmatrix} c \\ d \end{bmatrix} \begin{bmatrix} a & b \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\Rightarrow \mathcal{M} = \{ W \in \mathbb{R}^{2 \times 2} \mid \text{rk}(W) \leq 1 \}$$

Is \mathcal{M} a variety or just a semialgebraic set?

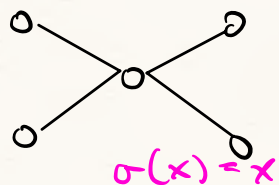
defined by $\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} = 0$

$$\alpha_L \circ \dots \circ \alpha_2 \circ \alpha_1, \text{ where } \alpha_i: \mathbb{R}^{d_{i-1}} \rightarrow \mathbb{R}^{d_i} \text{ linear}$$

$$\Rightarrow \mathcal{M} = \{ W \in \mathbb{R}^{d_L \times d_0} \mid \text{rk}(W) \leq \min \{ d_0, d_1, \dots, d_L \} \}$$

Is \mathcal{M} a variety or just a semialgebraic set?

Linear MLPs:



$$\begin{bmatrix} c \\ d \end{bmatrix} \begin{bmatrix} a & b \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\Rightarrow \mathcal{M} = \{ W \in \mathbb{R}^{2 \times 2} \mid \text{rk}(W) \leq 1 \}$$

Is \mathcal{M} a variety or just a semialgebraic set?

defined by $\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} = 0$

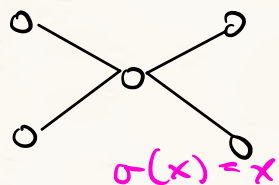
$$\alpha_L \circ \dots \circ \alpha_2 \circ \alpha_1, \text{ where } \alpha_i : \mathbb{R}^{d_{i-1}} \rightarrow \mathbb{R}^{d_i} \text{ linear}$$

$$\Rightarrow \mathcal{M} = \{ W \in \mathbb{R}^{d_L \times d_0} \mid \text{rk}(W) \leq \underbrace{\min \{d_0, d_1, \dots, d_L\}}_r \}$$

Is \mathcal{M} a variety or just a semialgebraic set?

defined by the vanishing of all $(r+1)$ -minors of W

Linear MLPs:



$$\begin{bmatrix} c \\ d \end{bmatrix} \begin{bmatrix} a & b \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\Rightarrow \mathcal{M} = \{ W \in \mathbb{R}^{2 \times 2} \mid \text{rk}(W) \leq 1 \}$$

Is \mathcal{M} a variety or just a semialgebraic set?

defined by $\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} = 0$

$$\alpha_L \circ \dots \circ \alpha_2 \circ \alpha_1, \text{ where } \alpha_i: \mathbb{R}^{d_{i-1}} \rightarrow \mathbb{R}^{d_i} \text{ linear}$$

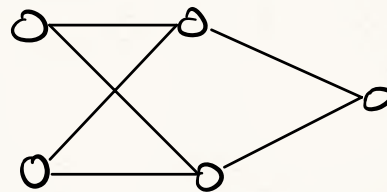
$$\Rightarrow \mathcal{M} = \{ W \in \mathbb{R}^{d_L \times d_0} \mid \text{rk}(W) \leq \underbrace{\min \{d_0, d_1, \dots, d_L\}}_r \}$$

Is \mathcal{M} a variety or just a semialgebraic set?

defined by the vanishing of all $(r+1)$ -minors of W

Monomial MLPs: $\sigma(x) = x^3$

$$\begin{bmatrix} e & f \end{bmatrix} \sigma \left(\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \right)$$



$$\Rightarrow \mathcal{M} \subseteq \mathbb{R}[x, y]_3$$

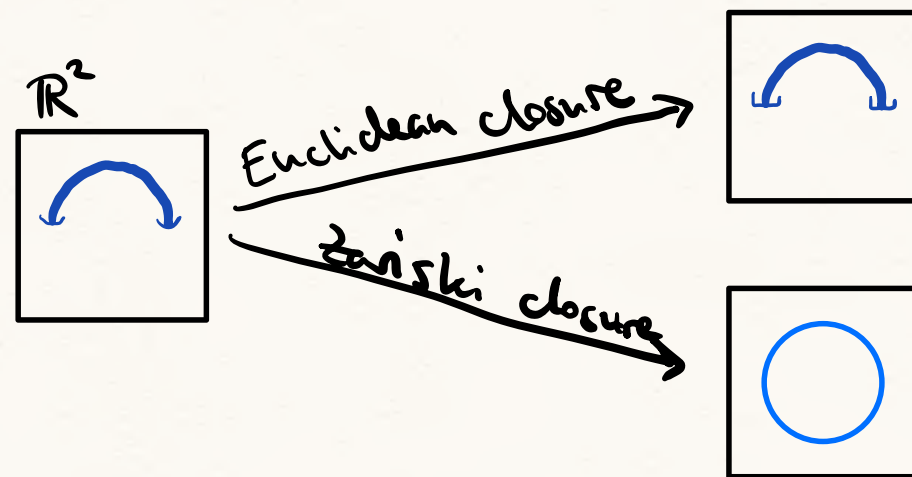
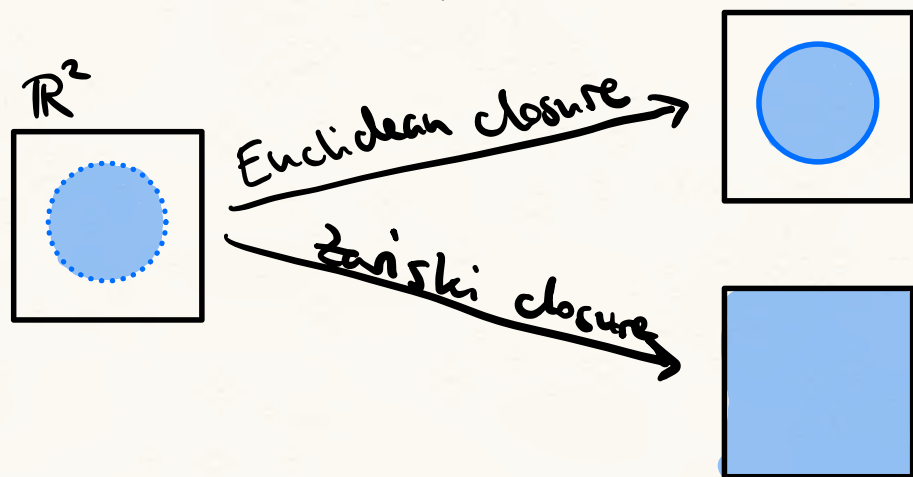
Is \mathcal{M} a variety or just a semialgebraic set?

Intermezzo: Zariski topology & Dimension

Zariski topology on \mathbb{R}^n : closed sets are the algebraic varieties

The Zariski topology is coarser than the Euclidean topology:

- Zariski closed implies Euclidean closed
- Zariski open implies Euclidean open



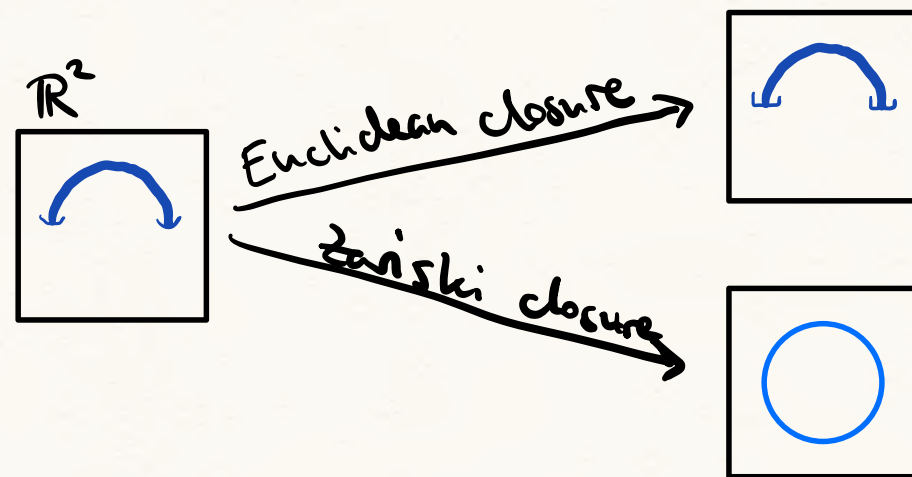
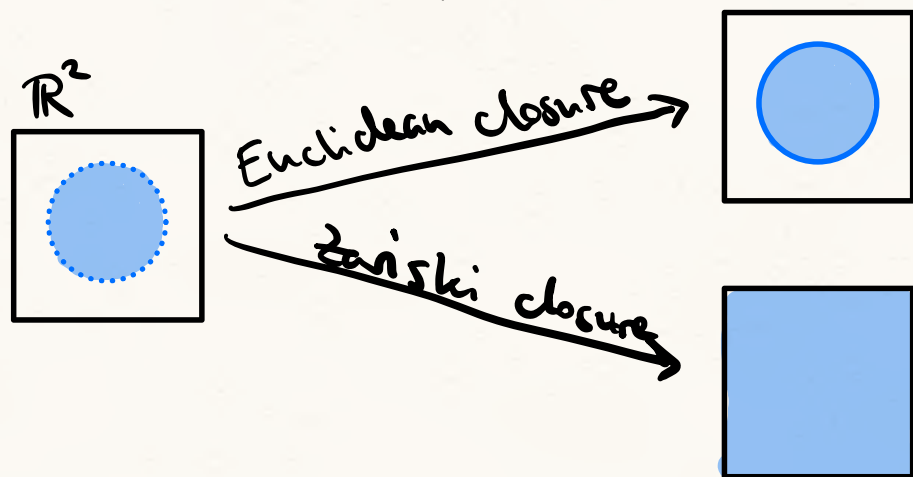
What are the Zariski closed sets in \mathbb{R}^1 ?

Intermezzo: Zariski topology & Dimension

Zariski topology on \mathbb{R}^n : closed sets are the algebraic varieties

The Zariski topology is coarser than the Euclidean topology:

- Zariski closed implies Euclidean closed
- Zariski open implies Euclidean open



What are the Zariski closed sets in \mathbb{R}^1 ?

What are the Zariski closed sets in \mathbb{R}^2 ?

\mathbb{R}^1 , finitely many points, \emptyset

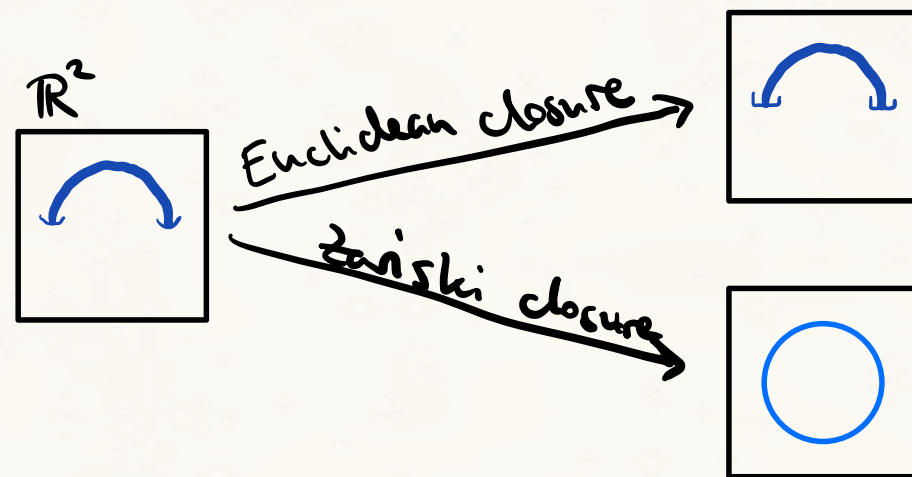
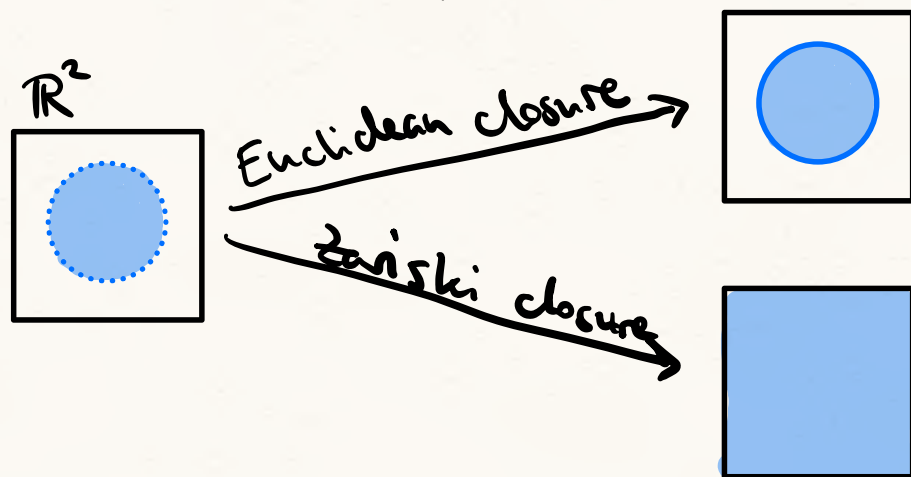


Intermezzo: Zariski topology & Dimension

Zariski topology on \mathbb{R}^n : closed sets are the algebraic varieties

The Zariski topology is coarser than the Euclidean topology:

- Zariski closed implies Euclidean closed
- Zariski open implies Euclidean open



What are the Zariski closed sets in \mathbb{R}^1 ?

\mathbb{R}^1 , finitely many points, \emptyset



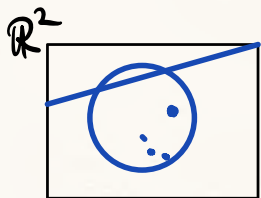
What are the Zariski closed sets in \mathbb{R}^2 ?

\mathbb{R}^2 , finite unions of algebraic curves & points, \emptyset



Intermezzo: Zariski topology & Dimension

A variety $X \subseteq \mathbb{R}^n$ is **irreducible** if it is not the union of 2 proper subvarieties, i.e., there are no varieties $X_1, X_2 \subseteq \mathbb{R}^n$ s.t. $X = X_1 \cup X_2$ & $\emptyset \neq X_i \subsetneq X$

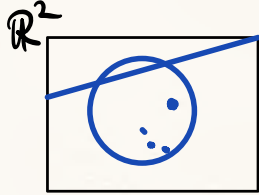
Ex.:  is reducible into 6 irreducible components

There is a subvariety $\Delta \subsetneq X$ such that $X \setminus \Delta$ is a smooth manifold of dimension k . If X is irreducible, k is the same for all such Δ : k is the **dimension** of X .

$$\dim(\bigcirc) = 1, \quad \dim(\bullet) = 0$$

Intermezzo: Zariski topology & Dimension

A variety $X \subseteq \mathbb{R}^n$ is **irreducible** if it is not the union of 2 proper subvarieties, i.e., there are no varieties $X_1, X_2 \subseteq \mathbb{R}^n$ s.t. $X = X_1 \cup X_2$ & $\emptyset \neq X_i \subsetneq X$

Ex.:  is reducible into 6 irreducible components

Zariski open in X

There is a subvariety $\Delta \subsetneq X$ such that $X \setminus \Delta$ is a smooth manifold of dimension k . If X is irreducible, k is the same for all such Δ : k is the **dimension** of X .

$$\dim(\bigcirc) = 1, \quad \dim(\bullet) = 0$$

In general: $X = \bigcup X_i$ ^{irreducible varieties}
 $\Rightarrow \dim(X) := \max_i \dim(X_i)$

For a semialgebraic set $X \subseteq \mathbb{R}^n$, define $\dim(X) := \dim(\overline{X})$ ^{Zariski closure}

$$\dim \left[\text{circle with dots and a line segment} \right] = \dim \left[\text{filled square} \right] = 2$$

Intermezzo: Zariski topology & Dimension

Let $\varphi: X \rightarrow \mathbb{R}^n$ morphism between irreducible varieties.

$\Rightarrow Y := \overline{\varphi(X)}$ ^{Zariski closure} is irreducible

Why?

Intermezzo: Zariski topology & Dimension

Let $\varphi: X \rightarrow \mathbb{R}^n$ morphism between irreducible varieties.

$\Rightarrow Y := \overline{\varphi(X)}$ is irreducible

← Zariski closure

Why?

almost everywhere in X /
for generic $x \in X$

Jacobian check: There is a subvariety $\Delta \subsetneq X$ such that for all $x \in X \setminus \Delta$, the rank of the Jacobi matrix $J_x(\varphi)$ equals $\dim(Y)$.

↳ practical test:

- ① choose random point $x \in X$
- ② compute rank $(J_x(\varphi))$
- ③ repeat until confident

$$\sigma(x) = x^3$$
$$\begin{bmatrix} e & f \end{bmatrix} \sigma \left(\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \right)$$

Compute dimension of $\mathcal{M} \subsetneq \mathbb{R}[x, y]_3$

Intermezzo: Zariski topology & Dimension

Let $\varphi: X \rightarrow \mathbb{R}^m$ morphism between irreducible varieties.

$\Rightarrow Y := \overline{\varphi(X)}$ is irreducible

← Zariski closure

Why?

almost everywhere in X /
for generic $x \in X$

Jacobian check: There is a subvariety $\Delta \subsetneq X$ such that for all $x \in X \setminus \Delta$, the rank of the Jacobi matrix $J_x(\varphi)$ equals $\dim(Y)$.

→ practical test:

- ① choose random point $x \in X$
- ② compute $\text{rank}(J_x(\varphi))$
- ③ repeat until confident

$$\sigma(x) = x^3$$
$$\begin{bmatrix} e & f \end{bmatrix} \sigma \left(\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \right)$$

Compute dimension of $\mathcal{M} \subsetneq \mathbb{R}[x, y]_3$

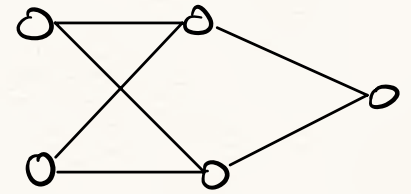
Fact: $\text{rank}(J_x(\varphi)) \leq \dim(Y)$ for all $x \in X$.

Why?

→ Finding a single point $x \in X$ with $\text{rank}(J_x(\varphi)) = m$ is enough to show that $Y = \mathbb{R}^m$.

Monomial MLPs: $\sigma(x) = x^3$

$$\begin{bmatrix} e & f \end{bmatrix} \sigma \left(\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \right)$$



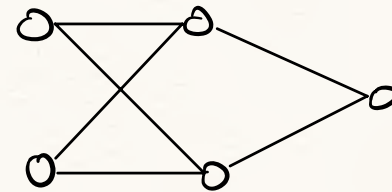
$$\Rightarrow \mathcal{M} \subseteq \mathbb{R}[x, y]_3$$

$\uparrow \quad \quad \uparrow$
 $\dim = 4$

Is \mathcal{M} a variety or just a semialgebraic set?

Monomial MLPs: $\sigma(x) = x^3$

$$[e \ f] \sigma \left(\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \right)$$



$$\Rightarrow \mathcal{M} \subseteq \mathbb{R}[x, y]_3$$

dim = 4

Is \mathcal{M} a variety or just a semialgebraic set?

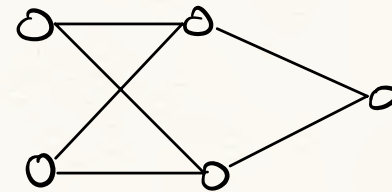
Is \mathcal{M} Euclidean closed?

And why do we care?

$$\begin{aligned} & e(ax+by)^3 + f(cx+dy)^3 \\ &= \underbrace{(a^3e + c^3f)}_A x^3 + \underbrace{3(a^2be + c^2df)}_B x^2y + \underbrace{3(ab^2e + cd^2f)}_C xy^2 + \underbrace{(b^3e + d^3f)}_D y^3 \end{aligned}$$

Monomial MLPs: $\sigma(x) = x^3$

$$[e \ f] \sigma \left(\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \right)$$



$$\Rightarrow \mathcal{M} \subseteq \mathbb{R}[x, y]_3$$

\uparrow $\dim = 4$ \uparrow

Is \mathcal{M} a variety or just a semialgebraic set?

Is \mathcal{M} Euclidean closed?

And why do we care?

parameter explosion!

$$e(ax+by)^3 + f(cx+dy)^3$$

$$= \underbrace{(a^3e + c^3f)}_A x^3 + \underbrace{3(a^2be + c^2df)}_B x^2y + \underbrace{3(ab^2e + cd^2f)}_C xy^2 + \underbrace{(b^3e + d^3f)}_D y^3$$

No, e.g. $A = 1$
 $B = 1$
 $C = 0$
 $D = 0$

$\notin \mathcal{M}$, but for $a=c=1, b=0, e=(-\frac{1}{3d}, f=\frac{1}{3d})$, we get

$$x^3 + x^2y + dx^2y^2 + \frac{1}{3}d^2y^3$$

$\downarrow d \rightarrow 0$

$$x^3 + x^2y$$

CNNs (convolutional neural nets)

on 1-dimensional signals without bias

$\alpha_L \circ \sigma \circ \dots \circ \sigma \circ \alpha_2 \circ \sigma \circ \alpha_1$, where each α_i is given by a 'Toeplitz' matrix of the form

$$\begin{bmatrix} w_0 & w_1 & \dots & w_s & \dots & w_{k-1} & 0 & \dots & \dots & 0 \\ 0 & \dots & 0 & w_0 & w_1 & \dots & w_{k-1} & 0 & \dots & 0 \\ \vdots & & & \ddots & & & & & & \\ 0 & \dots & \dots & 0 & w_0 & w_1 & \dots & w_{k-1} & \dots & 0 \end{bmatrix}$$

stride (pointing to w_s)
filter size (pointing to w_{k-1})

Proposition: If $\sigma(x) = x^r$, then CNN neuromanifold \mathcal{M} is Euclidean closed.

CNNs (convolutional neural nets)

on 1-dimensional signals without bias

$\alpha_L \circ \sigma \circ \dots \circ \sigma \circ \alpha_2 \circ \sigma \circ \alpha_1$, where each α_i is given by a 'Toeplitz' matrix of the form

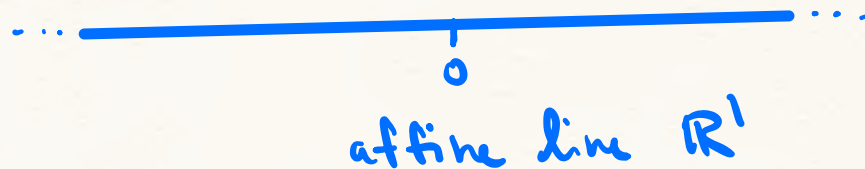
$$\begin{bmatrix} w_0 & w_1 & \dots & w_s & \dots & w_{k-1} & 0 & \dots & \dots & 0 \\ 0 & \dots & 0 & w_0 & w_1 & \dots & w_{k-1} & 0 & \dots & 0 \\ \vdots & & \ddots & & \ddots & & \ddots & & & \vdots \\ 0 & \dots & \dots & 0 & w_0 & w_1 & \dots & w_{k-1} & \dots & 0 \end{bmatrix}$$

stride (pointing to w_s)
filter size (pointing to w_{k-1})

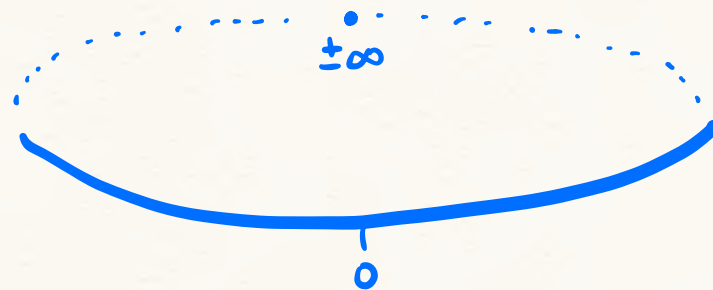
Proposition: If $\sigma(x) = x^r$, then CNN neuromanifold \mathcal{M} is Euclidean closed.

↳ Reason: $\Theta \longrightarrow \mathcal{M}$ is a **projective morphism**
 $\theta \longmapsto \mu(\theta, \cdot) : X \rightarrow Y$

Issue: Affine space is **not** compact

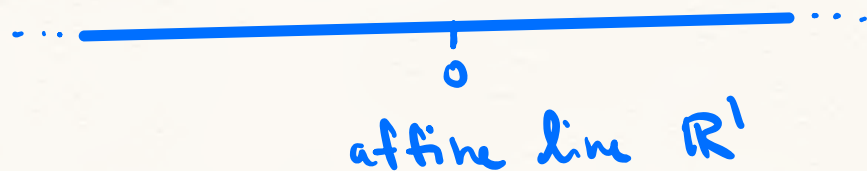


Projective space is compact 😊



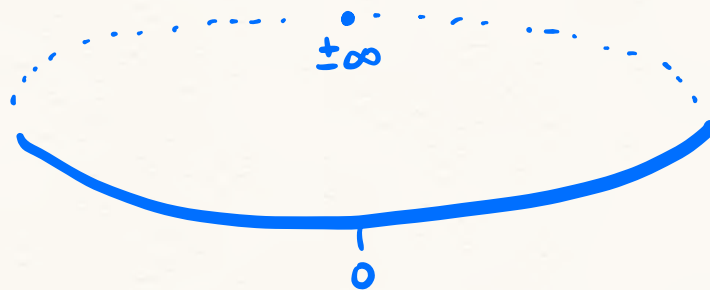
projective line $\mathbb{P}_{\mathbb{R}}^1 = \mathbb{R}^1 \cup \{\pm\infty\}$

Issue: Affine space is **not** compact



affine line \mathbb{R}^1

Projective space is compact 😊

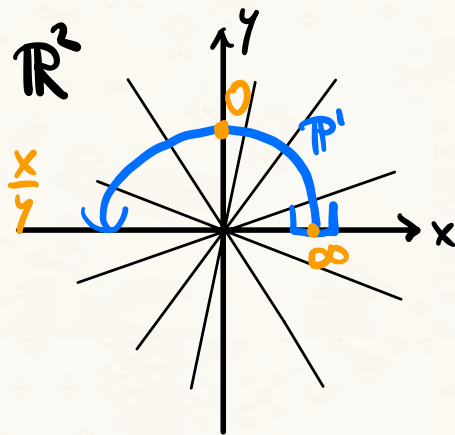


projective line $\mathbb{P}_\mathbb{R}^1 = \mathbb{R}^1 \cup \{\pm\infty\}$

standard construction:

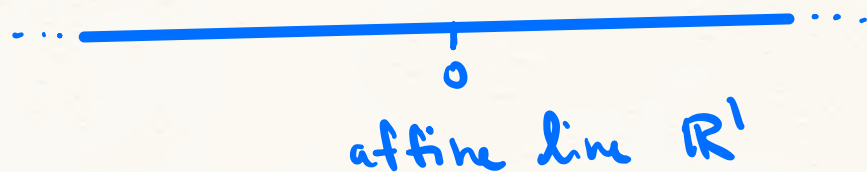
$$\mathbb{P}_\mathbb{R}^n = (\mathbb{R}^{n+1} \setminus \{0\}) / \sim, \text{ where}$$

$$u \sim v \iff \exists \lambda \in \mathbb{R} \setminus \{0\} : u = \lambda v$$



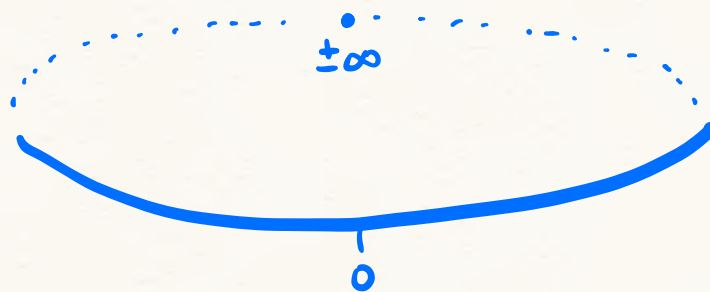
$\mathbb{P}_\mathbb{R}^n$ = set of lines
in \mathbb{R}^{n+1}
through origin

Issue: Affine space is **not** compact



affine line \mathbb{R}^1

Projective space is compact 😊



projective line $\mathbb{P}_\mathbb{R}^1 = \mathbb{R}^1 \cup \{\pm\infty\}$

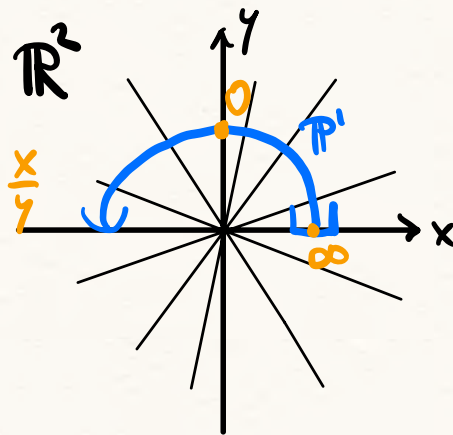
standard construction:

$$\mathbb{P}_\mathbb{R}^n = (\mathbb{R}^{n+1} \setminus \{0\}) / \sim, \text{ where}$$

$$u \sim v \iff \exists \lambda \in \mathbb{R} \setminus \{0\} : u = \lambda v$$

$\mathbb{P}_\mathbb{R}^n$ is the sphere in \mathbb{R}^{n+1} after identifying antipodal points

$\Rightarrow \mathbb{P}_\mathbb{R}^n$ is compact in the quotient topology of the Euclidean topology on \mathbb{R}^{n+1}



$\mathbb{P}_\mathbb{R}^n$ = set of lines in \mathbb{R}^{n+1} through origin

Standard fact from topology:

$\varphi: T_1 \rightarrow T_2$ continuous map between topological spaces,
 T_1 compact
 $\Rightarrow \text{im}(\varphi)$ is compact

Standard fact from topology:

$\varphi: T_1 \rightarrow T_2$ continuous map between topological spaces,
 T_1 compact
 $\Rightarrow \text{im}(\varphi)$ is compact

not compact ∇

$$\varphi_{\text{MLP}}: \mathbb{R}^{2 \times 2} \times \mathbb{R}^{1 \times 2} \longrightarrow \mathbb{R}[x, y]_3$$
$$\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}, [e \ f] \right) \longmapsto [e \ f] \sigma \left(\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \right)$$

$\sigma(x) = x^3$

} continuous ∇

Can we projectivize φ_{MLP} ?

$$\varphi_{MLP}(\alpha \begin{bmatrix} a & b \\ c & d \end{bmatrix}, \beta [e \ f]) = \beta [e \ f] \sigma \left(\alpha \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \right) = \alpha^3 \beta \varphi_{MLP} \left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}, [e \ f] \right)$$

so φ_{MLP} is well-behaved under scaling the factors
and it makes sense to consider

$$\tilde{\varphi}_{MLP}: \mathbb{P}_{\mathbb{R}}^3 \times \mathbb{P}_{\mathbb{R}}^1 \longrightarrow \mathbb{P}_{\mathbb{R}}^3$$

$$\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}, [e \ f] \right) \longmapsto \left[\begin{aligned} &(a^3 e + c^3 f) x^3 + 3(a^2 b e + c^2 d f) x^2 y \\ &+ 3(a b^2 e + c d^2 f) x y^2 + (b^3 e + d^3 f) y^3 \end{aligned} \right]$$

defined up to scaling!

BUT ...

what is the issue?

$$\varphi_{\text{MLP}}(\alpha \begin{bmatrix} a & b \\ c & d \end{bmatrix}, \beta [e \ f]) = \beta [e \ f] \sigma \left(\alpha \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \right) = \alpha^3 \beta \varphi_{\text{MLP}} \left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}, [e \ f] \right)$$

so φ_{MLP} is well-behaved under scaling the factors
and it makes sense to consider

$$\tilde{\varphi}_{\text{MLP}}: \mathbb{P}_{\mathbb{R}}^3 \times \mathbb{P}_{\mathbb{R}}^1 \longrightarrow \mathbb{P}_{\mathbb{R}}^3$$

$$\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}, [e \ f] \right) \longmapsto \left[\begin{aligned} &(a^3 e + c^3 f) x^3 + 3(a^2 b e + c^2 d f) x^2 y \\ &+ 3(a b^2 e + c d^2 f) x y^2 + (b^3 e + d^3 f) y^3 \end{aligned} \right]$$

defined up to scaling!

BUT $\tilde{\varphi}_{\text{MLP}}$ is not defined everywhere!

$$\text{E.g. } \varphi_{\text{MLP}} \left(\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}, [1 \ -1] \right) = 0 \notin \mathbb{P}_{\mathbb{R}}^3$$

cannot apply
topology fact!

Compute all points in $\mathbb{P}_R^3 \times \mathbb{P}_R^1$, where $\tilde{\varphi}_{MLP}$ is not defined.

This is called the **base locus** of $\tilde{\varphi}_{MLP}$.

Standard fact from topology:

$\varphi: T_1 \rightarrow T_2$ continuous map between topological spaces,
 T_1 compact
 $\Rightarrow \text{im}(\varphi)$ is compact

$$\varphi_{\text{CNN}}: \mathbb{R}^3 \times \mathbb{R}^2 \rightarrow \mathbb{R}[x_1, \dots, x_5]_3$$

$$((a, b, c), (e, f)) \mapsto [e \ f] \sigma \left(\begin{bmatrix} a & b & c & 0 & 0 \\ 0 & 0 & a & b & c \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_5 \end{bmatrix} \right)$$

\uparrow
 $\sigma(x) = x^3$

can be projectivized: $\tilde{\varphi}_{\text{CNN}}: \mathbb{P}_{\mathbb{R}}^2 \times \mathbb{P}_{\mathbb{R}}^1 \rightarrow \mathbb{P}(\mathbb{R}[x_1, \dots, x_5]_3)$

$$([a, b, c], [e, f]) \mapsto [e \ f] \sigma \left(\begin{bmatrix} a & b & c & 0 & 0 \\ 0 & 0 & a & b & c \end{bmatrix} x \right)$$

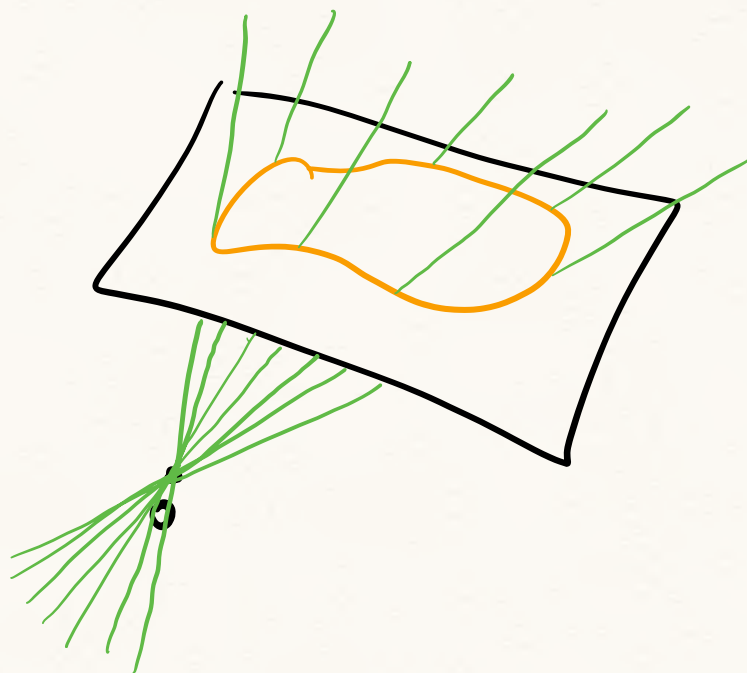
Compute: $\tilde{\varphi}_{\text{CNN}}$ is defined everywhere, i.e.,
 its base locus is empty.

} can apply
 topology fact



Hence: $\text{im}(\tilde{\varphi}_{\text{CNN}}) \subseteq \mathbb{P}(\mathbb{R}[x_1, \dots, x_5]_3)$ is compact (in Euclidean quotient top.).

Since $\text{im}(\varphi_{\text{CNN}}) \subseteq \mathbb{R}[x_1, \dots, x_5]_3$ is the **affine cone** over $\text{im}(\tilde{\varphi}_{\text{CNN}})$,
it is closed (in Euclidean topology).



replace each projective
point by the affine line
it represents

Proposition: If $\sigma(x) = x^r$, then CVN neuromanifold \mathcal{M} is Euclidean closed.

Reason: $\Theta \longrightarrow \mathcal{M}$ is a projective morphism
 $\theta \longmapsto \mu(\theta, \cdot) : X \rightarrow Y$

Proposition: If $\sigma(x) = x^r$, then CNV neuromanifold \mathcal{M} is Euclidean closed.

↳ Reason: $\Theta \longrightarrow \mathcal{M}$ is a **projective morphism**
 $\theta \longmapsto \mu(\theta, \cdot) : X \rightarrow Y$

Example: A linear CNV ($\sigma(x) = x$):

$$\varphi : \mathbb{R}^3 \times \mathbb{R}^2 \longrightarrow \mathbb{R}[x_1, \dots, x_5]_1 \cong \mathbb{R}^5$$

$$((a, b, c), (e, f)) \longmapsto [e \ f] \begin{bmatrix} a & b & c & 0 & 0 \\ 0 & 0 & a & b & c \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_5 \end{bmatrix}, \quad \mathcal{M} := \text{im}(\varphi)$$

↖ Zariski closure

↪ $\overline{\mathcal{M}}$ is a hypersurface and thus defined by a single equation.

① Compute that $\dim(\mathcal{M}) = 4$.

② Find that equation!

③ Check that base locus of projectivization $\tilde{\varphi} : \mathbb{P}_{\mathbb{R}}^2 \times \mathbb{P}_{\mathbb{R}}^1 \rightarrow \mathbb{P}_{\mathbb{R}}^4$ is empty.

④ Find a point in $\overline{\mathcal{M}} \setminus \mathcal{M}$.

Proposition: If $\sigma(x) = x^r$, then CNM neuromanifold \mathcal{M} is Euclidean closed.

↳ Reason: $\Theta \longrightarrow \mathcal{M}$ is a **projective morphism**
 $\theta \longmapsto \mu(\theta, \cdot) : X \rightarrow Y$

Example: A linear CNM ($\sigma(x) = x$):

$$\varphi : \mathbb{R}^3 \times \mathbb{R}^2 \longrightarrow \mathbb{R}[x_1, \dots, x_5]_1 \cong \mathbb{R}^5$$

$$((a, b, c), (e, f)) \longmapsto [e \ f] \begin{bmatrix} a & b & c & 0 & 0 \\ 0 & 0 & a & b & c \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_5 \end{bmatrix} = A x_1 + B x_2 + C x_3 + D x_4 + E x_5$$

$\mathcal{M} := \text{im}(\varphi)$

↖ Zariski closure

① Compute that $\dim(\mathcal{M}) = 4$.

⇒ $\bar{\mathcal{M}}$ is a hypersurface and thus defined by a single equation.

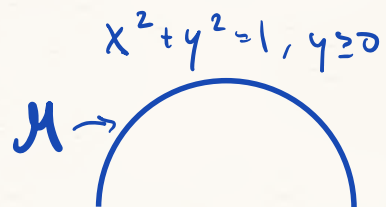
② Find that equation! $AD^2 + B^2E - BCD = 0$

③ Check that base locus of projectivization $\tilde{\varphi} : \mathbb{P}_{\mathbb{R}}^2 \times \mathbb{P}_{\mathbb{R}}^1 \rightarrow \mathbb{P}_{\mathbb{R}}^4$ is empty.

④ Find a point in $\bar{\mathcal{M}} \setminus \mathcal{M}$. $B = C = D = 0, A = E = 1$

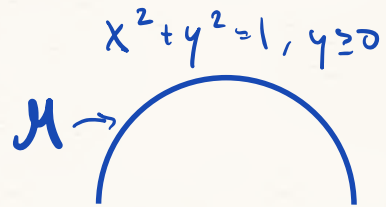
Euclidean boundary?

What is the Euclidean boundary of M ? (And why do we care?)



Euclidean boundary?

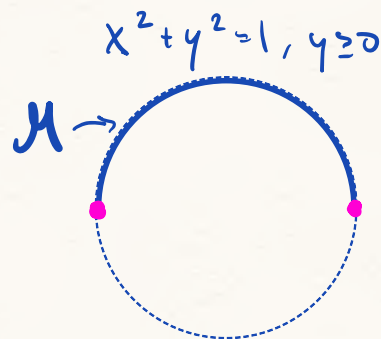
What is the Euclidean boundary of M ? (And why do we care?)



Euclidean boundary of $M \subseteq \mathbb{R}^2$ is M ,
so its interior is empty

Euclidean boundary?

What is the Euclidean boundary of M ? (And why do we care?)



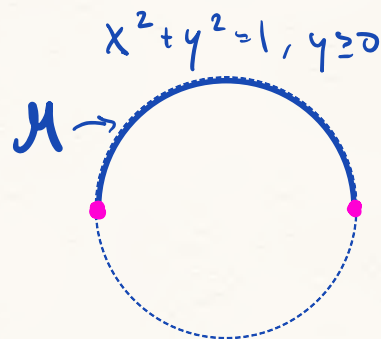
Euclidean boundary of $M \subseteq \mathbb{R}^2$ is M ,
so its interior is empty

Its boundary in the Euclidean topology on \bar{M} (inherited from \mathbb{R}^2)
is 2 points.

In general: We write ∂M for the relative Euclidean boundary of M inside \bar{M} .

Euclidean boundary?

What is the Euclidean boundary of M ? (And why do we care?)

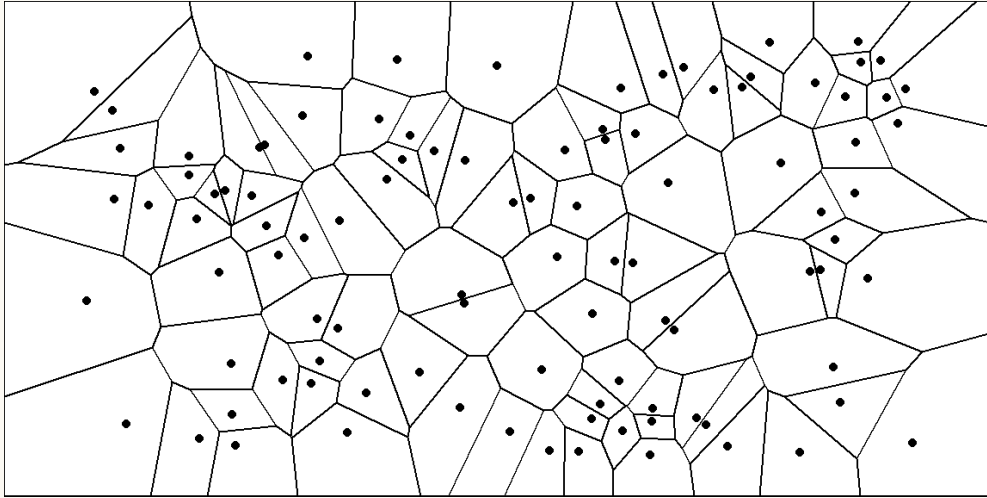


Euclidean boundary of $M \subseteq \mathbb{R}^2$ is M ,
so its interior is empty

Its boundary in the Euclidean topology on \bar{M} (inherited from \mathbb{R}^2)
is 2 points.

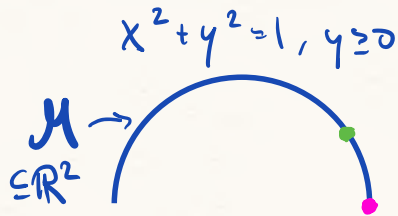
In general: We write ∂M for the relative Euclidean boundary of M inside \bar{M} .

Voronoi cells



For $S \subseteq \mathbb{R}^n$, the **Voronoi cell** at $p \in S$ is

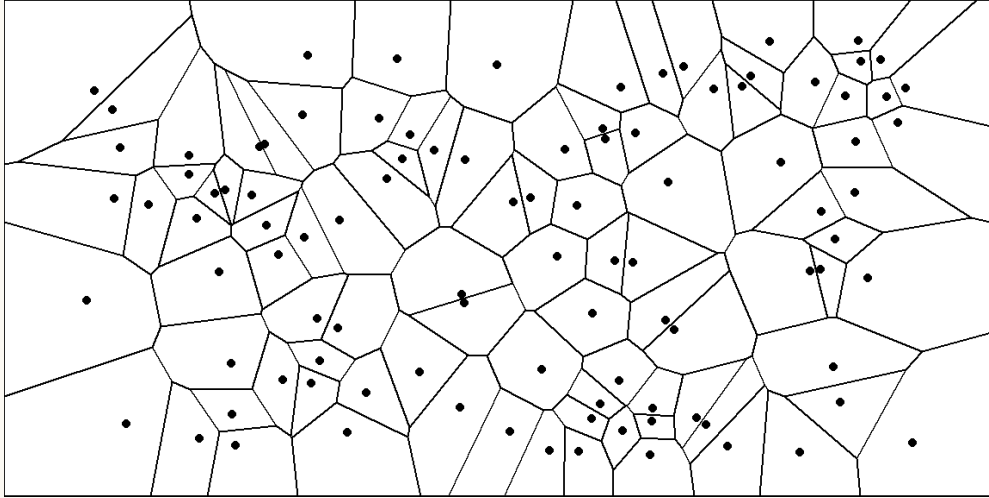
$$\text{Vor}_S(p) := \{u \in \mathbb{R}^n \mid \forall q \in S, q \neq p: \|p - u\|_2 < \|q - u\|_2\}$$



What is the Voronoi cell at •?

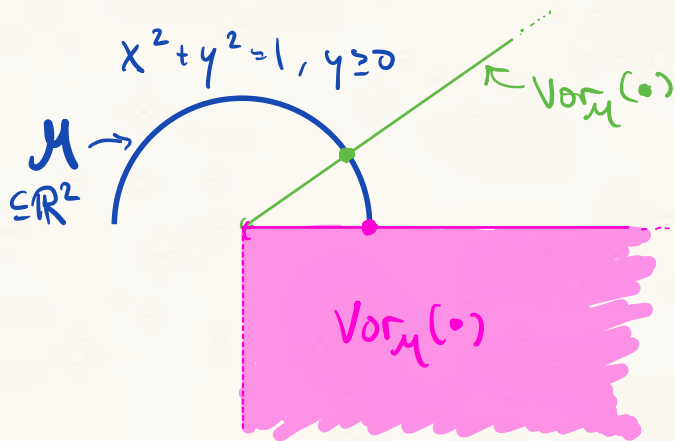
What is the Voronoi cell at •?

Voronoi cells



For $S \subseteq \mathbb{R}^n$, the **Voronoi cell** at $p \in S$ is

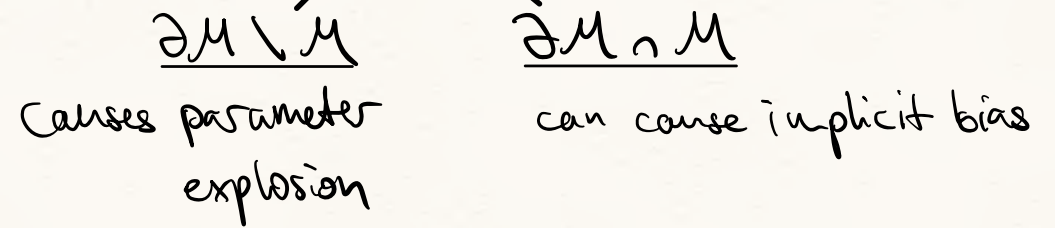
$$\text{Vor}_S(p) := \{u \in \mathbb{R}^n \mid \forall q \in S, q \neq p: \|p - u\|_2 < \|q - u\|_2\}$$



The 2 relative boundary points are the only points on M with full-dimensional Voronoi cells!
 \Rightarrow **implicit bias** towards ∂M

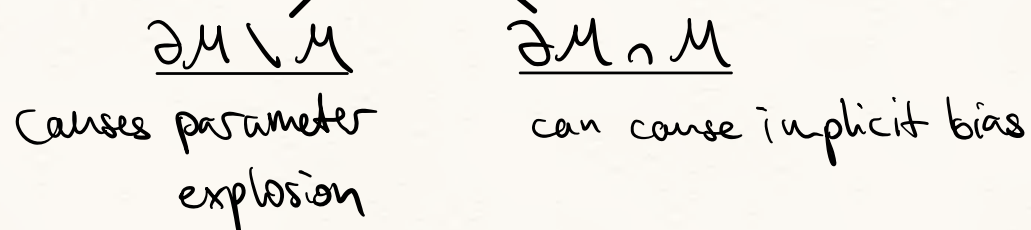
points in ∂M are global minima with positive probability on data u

Relative Euclidean boundary $\partial\mathcal{M}$



How to compute $\partial\mathcal{M}$?

Relative Euclidean boundary ∂M



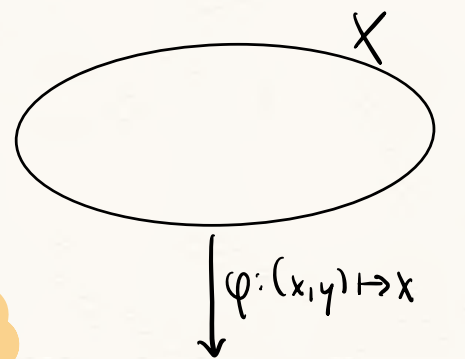
How to compute ∂M ?

Let $\varphi: X \rightarrow \mathbb{R}^n$ morphism between irreducible varieties, $Y := \overline{\varphi(X)}$. ← Zariski closure

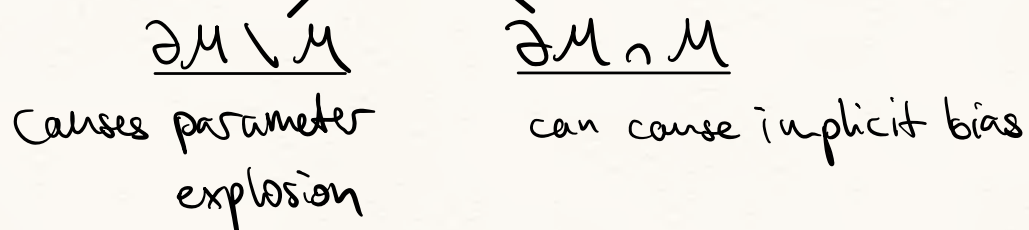
The **ramification locus** of φ is $\text{Ram}(\varphi) := \{x \in X \mid \text{rank } J_x(\varphi) < \dim Y\}$.

The **branch locus** of φ is $\text{Br}(\varphi) := \varphi(\text{Ram}(\varphi))$.

What are $\text{Ram}(\varphi)$ &
 $\text{Br}(\varphi)$ in this example?



Relative Euclidean boundary ∂M



How to compute ∂M ?

Let $\varphi: X \rightarrow \mathbb{R}^n$ morphism between irreducible varieties, $Y := \overline{\varphi(X)}$. ← Zariski closure

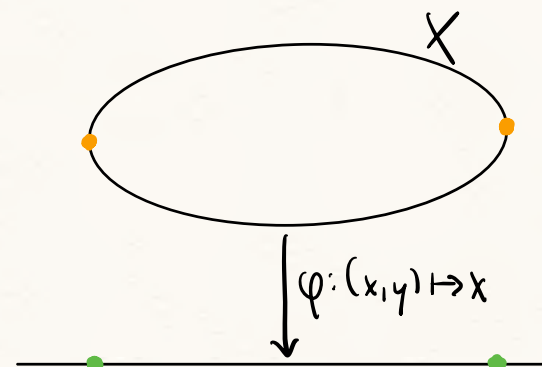
The **ramification locus** of φ is $\text{Ram}(\varphi) := \{x \in X \mid \text{rank } J_x(\varphi) < \dim Y\}$.

The **branch locus** of φ is $\text{Br}(\varphi) := \varphi(\text{Ram}(\varphi))$.

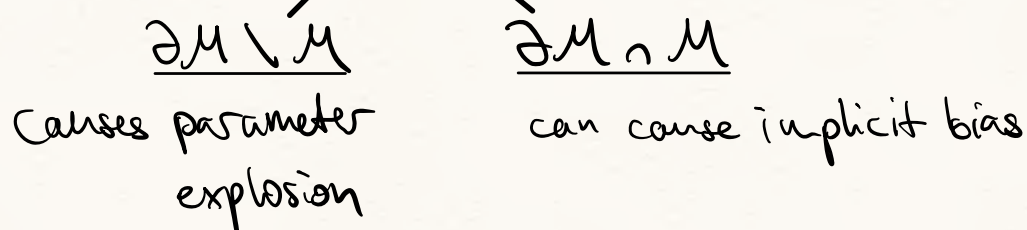
Lemma: $\dim(\varphi) \cap \text{im}(\varphi) \subseteq \text{Br}(\varphi)$

↳ Why?

↳ Is this an equality?



Relative Euclidean boundary ∂M

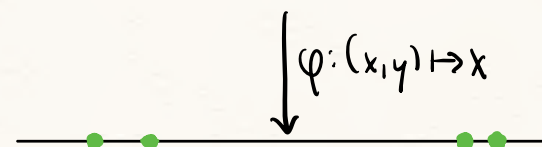
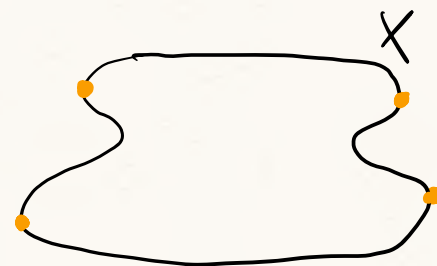


How to compute ∂M ?

Let $\varphi: X \rightarrow \mathbb{R}^m$ morphism between irreducible varieties, $Y := \overline{\varphi(X)}$. ← Zariski closure

The **ramification locus** of φ is $\text{Ram}(\varphi) := \{x \in X \mid \text{rank } J_x(\varphi) < \dim Y\}$.

The **branch locus** of φ is $\text{Br}(\varphi) := \varphi(\text{Ram}(\varphi))$.



Lemma: $\dim(\varphi) \cap \text{im}(\varphi) \subseteq \text{Br}(\varphi)$

↳ Why? essentially inverse function theorem...

↳ Is this an equality? **not in general**

Compute branch locus ($\& \partial M$) in the following examples:
 \nwarrow challenge!

① A linear CNN ($\sigma(x) = x$):

$$\begin{aligned} \varphi: \mathbb{R}^3 \times \mathbb{R}^2 &\longrightarrow \mathbb{R}[x_1, \dots, x_5]_1 \cong \mathbb{R}^5 \\ ((a, b, c), (e, f)) &\longmapsto [e \ f] \begin{bmatrix} a & b & c & 0 & 0 \\ 0 & 0 & a & b & c \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_5 \end{bmatrix} \end{aligned}$$

② A monomial CNN:

$$\begin{aligned} \varphi: \mathbb{R}^3 \times \mathbb{R}^2 &\longrightarrow \mathbb{R}[x_1, \dots, x_5]_3 \\ ((a, b, c), (e, f)) &\longmapsto [e \ f] \sigma \left(\begin{bmatrix} a & b & c & 0 & 0 \\ 0 & 0 & a & b & c \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_5 \end{bmatrix} \right) \end{aligned}$$

\nwarrow $\sigma(x) = x^3$

③ A monomial MLP:

$$\begin{aligned} \varphi: \mathbb{R}^{2 \times 2} \times \mathbb{R}^{1 \times 2} &\longrightarrow \mathbb{R}[x, y]_3 \\ \left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}, [e \ f] \right) &\longmapsto [e \ f] \sigma \left(\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \right) \end{aligned}$$

\nwarrow $\sigma(x) = x^3$

Compute branch locus (∂M) in the following examples:
 ↗ challenge!

① A linear CNN ($\sigma(x) = x$):

$$\psi: \mathbb{R}^3 \times \mathbb{R}^2 \rightarrow \mathbb{R}[x_1, \dots, x_5]_1 \cong \mathbb{R}^5$$

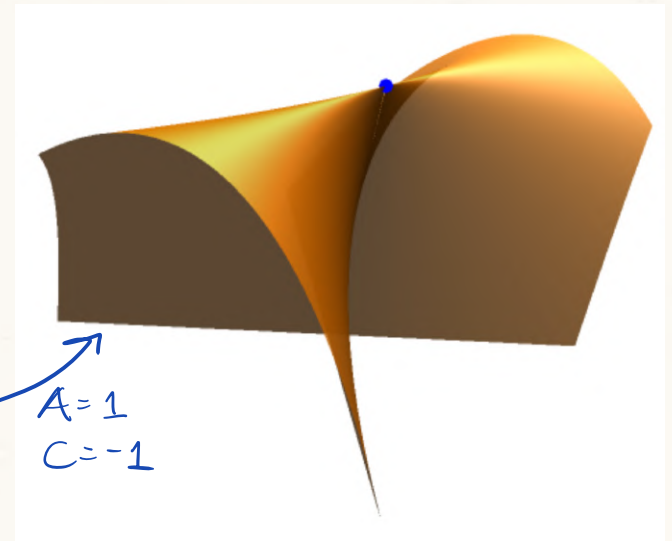
$$((a, b, c), (e, f)) \mapsto [e \ f] \begin{bmatrix} a & b & c & 0 & 0 \\ 0 & 0 & a & b & c \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_5 \end{bmatrix} = \underbrace{ae}_{A}x_1 + \underbrace{be}_{B}x_2 + \underbrace{(ce+af)}_Cx_3 + \underbrace{bf}_Dx_4 + \underbrace{cf}_Ex_5$$

$$\text{Ram}(\psi) = \{e=f=0\} \cup \{b=0 = \det \begin{bmatrix} a & c \\ e & f \end{bmatrix}\}$$

$$\overline{\text{Br}(\psi)} = \{0=B=D=C^2-4AE\}$$

$$M \subseteq \{AD^2+B^2E-BCD=0, C^2-4AE \geq 0\}$$

↗ [in fact equality!]



For any (A, C, E) with $C^2 = 4AE$, find sequence $(A_\epsilon, C_\epsilon, E_\epsilon) \rightarrow (A, C, E)$
 such that $B_\epsilon = 0, D_\epsilon = 0, \rightsquigarrow \in \bar{M}$
 $0 > C_\epsilon^2 - 4A_\epsilon E_\epsilon \rightsquigarrow \notin M$

$$\Rightarrow \partial M = \text{Br}(\psi) = \overline{\text{Br}(\psi)}$$

Compute branch locus ($\& \partial M$) in the following examples:
 \nwarrow challenge!

② A monomial CNN:

$$\psi: \mathbb{R}^3 \times \mathbb{R}^2 \longrightarrow \mathbb{R}[x_1, \dots, x_5]_3$$

$$((a, b, c), (e, f)) \longmapsto [e \ f] \overset{\sigma}{\left(\begin{bmatrix} a & b & c & 0 & 0 \\ 0 & 0 & a & b & c \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_5 \end{bmatrix} \right)}$$

\uparrow
 $\sigma(x) = x^3$

$$\text{Ram}(\psi) = \{e = f = 0\} \cup \{a = b = c = 0\}$$

$$\text{Br}(\psi) = \{0\}$$

$$\Rightarrow \partial M \underset{\substack{\uparrow \\ \text{Euclidean} \\ \text{closed}}}{=} \partial M \cap M = \{0\}$$

Since M is scaling invariant (i.e., a projective variety where $\text{Br}(\tilde{\psi}) = \emptyset$),
 $M = \bar{M}$ & $\partial M = \emptyset$

Compute branch locus ($\& \partial M$) in the following examples:
 \uparrow challenge!

② A monomial CNN:

$$\psi: \mathbb{R}^3 \times \mathbb{R}^2 \longrightarrow \mathbb{R}[x_1, \dots, x_5]_3$$

$$((a, b, c), (e, f)) \longmapsto [e \ f] \underset{\substack{\uparrow \\ \sigma(x) = x^3}}{\sigma} \left(\begin{bmatrix} a & b & c & 0 & 0 \\ 0 & 0 & a & b & c \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_5 \end{bmatrix} \right)$$

$$\text{Ram}(\psi) = \{e=f=0\} \cup \{a=b=c=0\}$$

$$\text{Br}(\psi) = \{0\}$$

$$\Rightarrow \partial M \underset{\substack{\uparrow \\ \text{Euclidean} \\ \text{closed}}}{=} \partial M \cap M = \{0\}$$

Theorem [Shahverdi, Maschke, K.]:
 For every monomial CNN with
 $\sigma(x) = x^r$, $r > 1$, without bias vectors:
 $\text{Ram}(\tilde{\psi}) = \emptyset$ & M is Zariski closed.

Since M is scaling invariant (i.e., a projective variety where $\text{Br}(\tilde{\psi}) = \emptyset$),
 $M = \bar{M}$ & $\partial M = \emptyset$

Compute branch locus ($\neq \partial M$) in the following examples:
 \nwarrow challenge!

(3) A monomial MLP:

$$\varphi: \mathbb{R}^{2 \times 2} \times \mathbb{R}^{1 \times 2} \longrightarrow \mathbb{R}[x, y]_3$$

$$\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}, [e \ f] \right) \longmapsto [e \ f] \overset{\sigma}{\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \right)} = e(ax+by)^3 + f(cx+dy)^3$$

$\sigma(x) = x^3$

$$\text{Ram}(\varphi) = \{e=0\} \cup \{f=0\} = \{\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} = 0\}$$

$$\rightarrow \text{Br}(\varphi) = \{(\alpha x + \beta y)^3 \mid \alpha, \beta \in \mathbb{R}\}$$

Compute branch locus ($\partial \mathcal{M}$) in the following examples:
 ↗ challenge!

(3) A monomial MLP:

$$\varphi: \mathbb{R}^{2 \times 2} \times \mathbb{R}^{1 \times 2} \longrightarrow \mathbb{R}[x, y]_3$$

$$\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}, [e \ f] \right) \longmapsto [e \ f] \overset{\sigma(x)=x^3}{\sigma} \left(\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \right) = e(ax+by)^3 + f(cx+dy)^3$$

$$= Ax^3 + Bx^2y + Cxy^2 + Dy^3$$

$$\text{Rank}(\varphi) = \{e=0\} \cup \{f=0\} = \{\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} = 0\}$$

$$\Rightarrow \text{Br}(\varphi) = \{(\alpha x + \beta y)^3 \mid \alpha, \beta \in \mathbb{R}\}$$

$$\Rightarrow \mathcal{M} \subseteq \{B^2C^2 - 4Ae^3 - 4B^3D - 27A^2D^2 + 18ABCD \leq 0\}$$

Recall: $\bar{\mathcal{M}} = \mathbb{R}[x, y]_3$

For $(\alpha x + \beta y)^3$, consider sequence $(\alpha x + \beta(y + \epsilon)) \cdot (\alpha x + \beta y) \cdot (\alpha x + \beta(y - \epsilon)) \notin \mathcal{M}$
 $\Rightarrow \partial \mathcal{M} = \text{Br}(\varphi)$

Compute branch locus ($\mathbb{R} \partial M$) in the following examples:
 ↗ challenge!

(3) A monomial MLP:

$$\varphi: \mathbb{R}^{2 \times 2} \times \mathbb{R}^{1 \times 2} \longrightarrow \mathbb{R}[x, y]_3$$

$$\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}, [e \ f] \right) \longmapsto [e \ f] \overset{\sigma}{\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \right)} = e(ax+by)^3 + f(cx+dy)^3$$

$\sigma(x) = x^3$

$$= Ax^3 + Bx^2y + Cxy^2 + Dy^3$$

$$\text{Ram}(\varphi) = \{e=0\} \cup \{f=0\} = \{\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} = 0\}$$

$$\Rightarrow \text{Br}(\varphi) = \{(\alpha x + \beta y)^3 \mid \alpha, \beta \in \mathbb{R}\}$$

discriminant of

$$\Rightarrow M \subseteq \{B^2C^2 - 4Ae^3 - 4B^3D - 27A^2D^2 + 18ABCD \leq 0\} = \text{Euclidean closure of } M$$

Recall: $\bar{M} = \mathbb{R}[x, y]_3$

For $(\alpha x + \beta y)^3$, consider sequence $(\alpha x + \beta(y + \varepsilon)) \cdot (\alpha x + \beta y) \cdot (\alpha x + \beta(y - \varepsilon)) \notin M$
 $\Rightarrow \partial M = \text{Br}(\varphi)$

not Euclidean closed

Challenge: Compute M !

Overview (no bias vectors)

	linear $\sigma(x) = x$	monomial $\sigma(x) = x^r, r > 1$
MLPs	M Zariski closed "determinantal varieties"	in general, M not Euclidean closed
CNNs	M Euclidean closed, but in general, not Zariski closed	M Zariski closed