

Singularities

Neuromanifolds $\mathcal{M}$ are **not** smooth manifolds!

Example: Linear MLPs

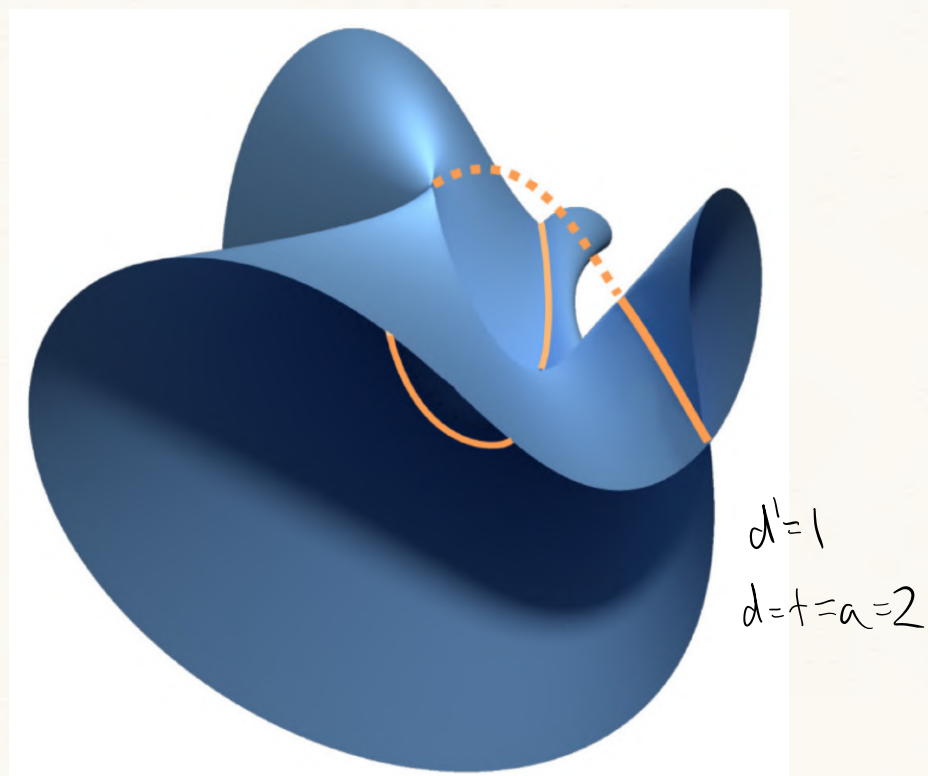
$$\mathcal{M} = \{W \in \mathbb{R}^{d_L \times d_O} \mid \text{rk}(W) \leq r\} \quad \text{Zariski closed} \quad (\leadsto \partial\mathcal{M} = \emptyset)$$

$$\text{Sing}(\mathcal{M}) = \{W \in \mathbb{R}^{d_L \times d_O} \mid \text{rk}(W) \leq r-1\} \quad \text{if } 0 < r < \min\{d_O, d_L\}$$

Example: unnormalized / linear / lightning self-attention mechanism

$$\begin{aligned} \mathbb{R}^{d \times t} &\longrightarrow \mathbb{R}^{d' \times t} \\ X &\longmapsto V X X^T K^T Q X \end{aligned}$$

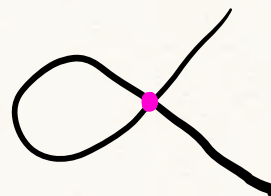
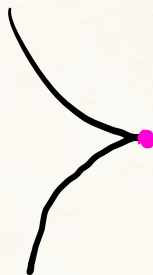
learnable parameters
 $V \in \mathbb{R}^{d' \times d}, K, Q \in \mathbb{R}^{a \times d}$



Singularities

$X \subseteq \mathbb{R}^n$ irreducible variety.

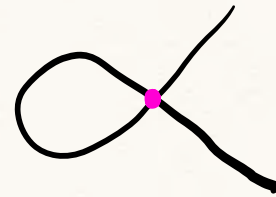
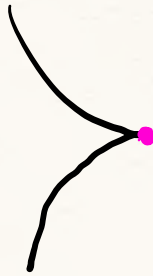
Intuitive definition: $x \in X$ is **singular** if X doesn't look like $\mathbb{R}^{\dim X}$ locally around x .



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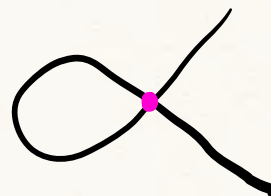
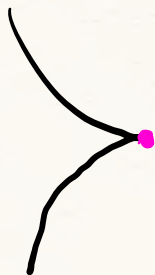


Formal definition: • **vanishing ideal** $\mathcal{I}_X := \{ f \in \mathbb{R}[x_1, \dots, x_n] \mid \forall x \in X, f(x) = 0 \}$

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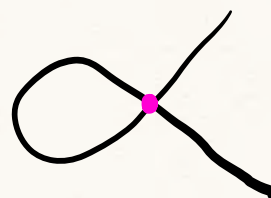
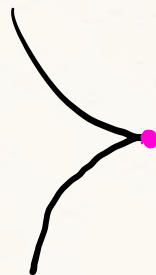
Formal definition: • **vanishing ideal** $I_X := \{f \in \mathbb{R}[x_1, \dots, x_n] \mid \forall x \in X, f(x) = 0\}$

- generating set $\{f_1, \dots, f_s\}$, i.e., $I_X = \{g_1 f_1 + \dots + g_s f_s \mid g_i \in \mathbb{R}[x_1, \dots, x_n]\}$
(exists by **Hilbert's basis theorem**)

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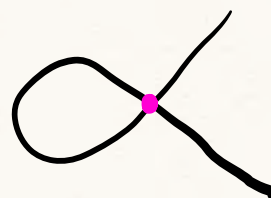
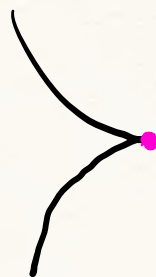
- jacobian $s \times n$ -matrix: $J = \left[\frac{\partial f_i}{\partial x_j} \right]_{i,j}$

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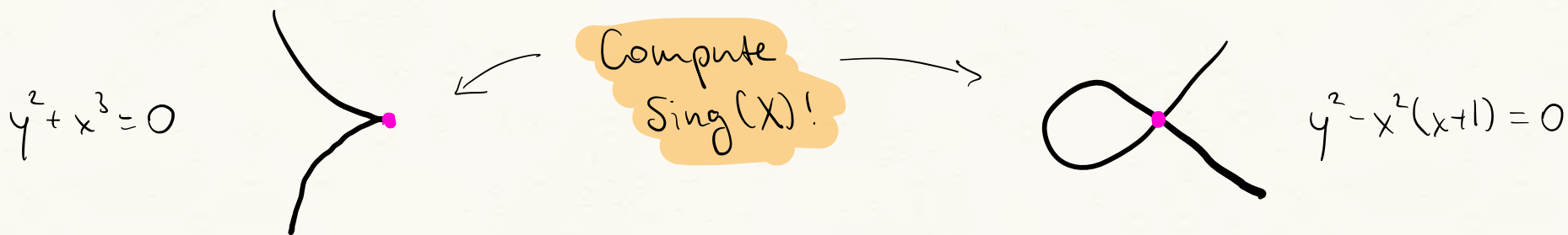
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 Such x are called **smooth / regular** (note: $\ker J(x) = T_x X \cong \mathbb{R}^{\dim X}$). **Why?**
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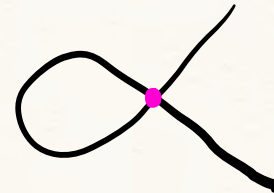
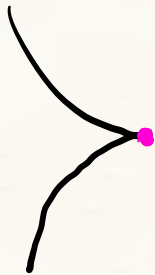


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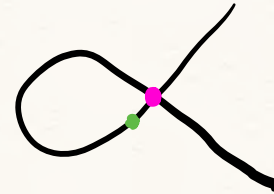
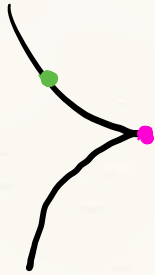
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Why do we care about singularities?

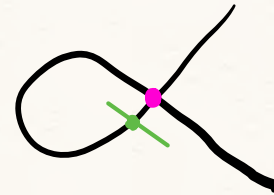
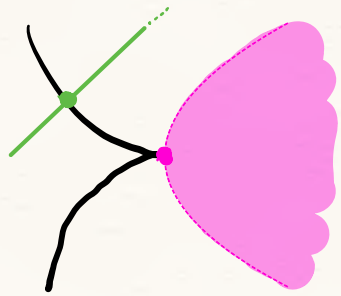


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What are the Voronoi cells at $\bullet$ and $\bullet$?

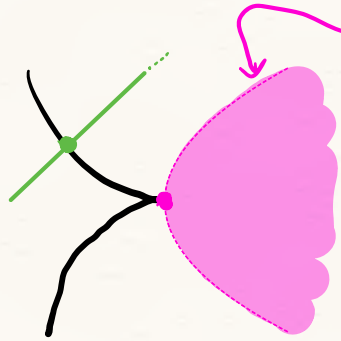
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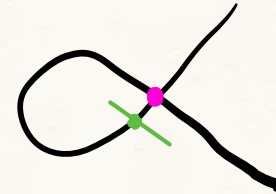
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Why do we care about singularities?

$$y^2 + x^3 = 0$$



Challenge: Compute this curve!



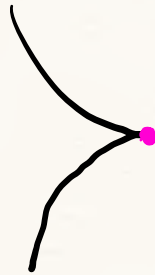
$$y^2 - x^2(x+1) = 0$$

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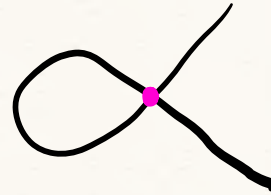
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$$\text{Br}(\varphi) = \{\cdot\}$$



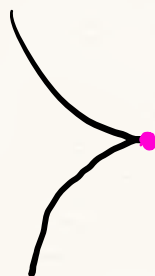
$$\varphi: t \mapsto (t^2-1, t(t^2-1))$$

$$|\bar{\varphi}'(\cdot)| = 2$$

(while $|\bar{\varphi}'(\cdot)| = 1$ for all other points)

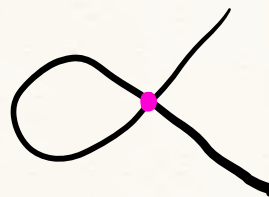
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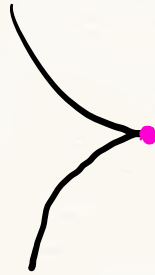
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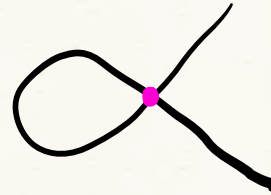
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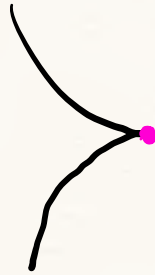
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Singularities on M can be caused by the branch locus or the special fibers of $\varphi: \Theta \rightarrow M$.

$\uparrow \bar{\varphi}'(f)$

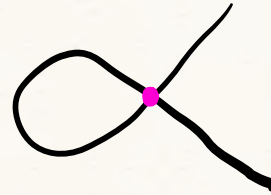
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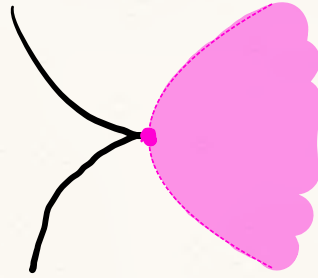
$\uparrow \bar{\varphi}'(f)$

$\varphi: t \mapsto t^3$ has smooth image although $\text{Br}(\varphi) = \{\emptyset\}$



Tradeoff: Good generalization vs. efficient optimization

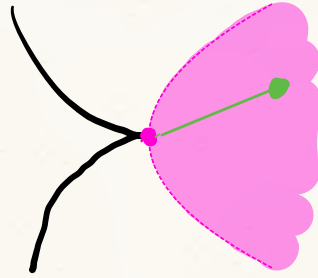
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Jacobian rank drop at $t=0$:
numerical instability close to $t=0$

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$\bullet$ is a **stable** solution for every $\bullet \in \text{Vor}_H(\bullet)$,
i.e., $\bullet$ stays minimizer when perturbing $\bullet$



MLP

$\sigma(x)$ = generic
polynomial
of large
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CNN

Some singularities known
(work in progress to determine all)

All singularities known.



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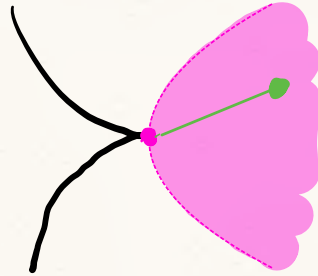
true in both
cases ☺

[Shahverdi, Marchetti,
K. 2025]

Conjecture. The singularities of neuromanifolds $\mathcal{M}$ correspond to (certain) subnetworks, i.e., networks of a smaller architecture that can be embedded into the given architecture.

Tradeoff: Good generalization vs. efficient optimization

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Jacobian rank drop at $t=0$:
numerical instability close to $t=0$

$\bullet$ is a **stable** solution for every $\bullet \in \text{Vor}_H(\bullet)$,
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and $\bullet$ is a **sparse** solution (conjecturally)

Fibers

$$\begin{array}{ccccc} \Theta & \xrightarrow{\varphi} & \mathcal{M} & \xrightarrow{L} & \mathbb{R} \\ \theta & \mapsto & f_\theta & & \end{array}$$

each minimizer $\hat{f} \in \mathcal{M}$ can give
many minimizers $\bar{\varphi}(\hat{f})$ in Θ

$\Leftarrow$

potentially many global minimizers $\hat{f}$
(in large model regime)

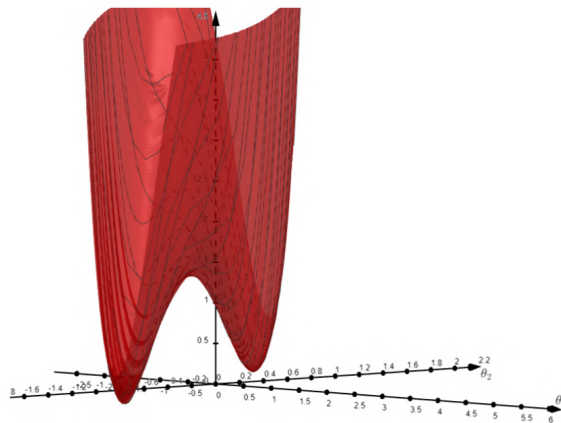
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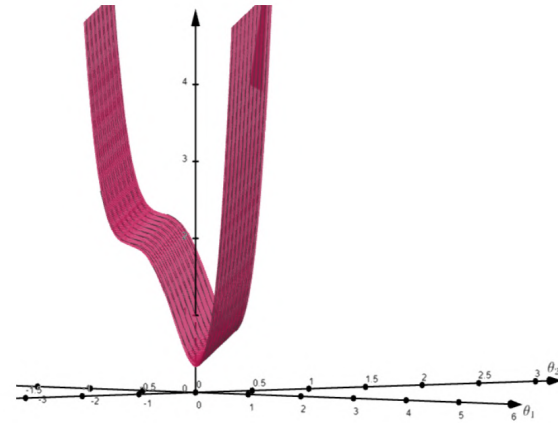
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(a) $\mu_1 : \begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix} \mapsto \begin{bmatrix} \frac{5}{4}\theta_1^2 + 5\theta_1\theta_2 + 5\theta_2^2 + \theta_1 + 2\theta_2 \\ \frac{1}{4}\theta_1^2 + \theta_1\theta_2 + \theta_2^2 + \frac{3}{2}\theta_1 + 2\theta_2 \end{bmatrix}$
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Figure 1. Loss landscapes of $\|\mu_i(\theta) - \begin{bmatrix} 1 \\ 0 \end{bmatrix}\|_2^2$.

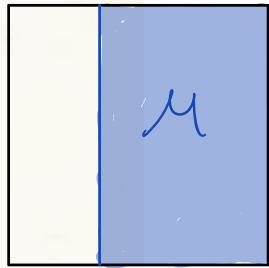
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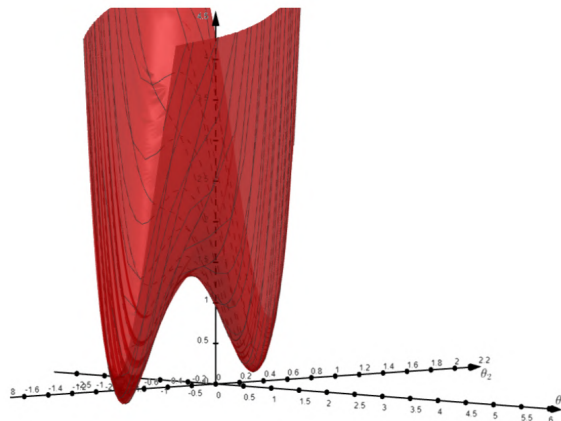
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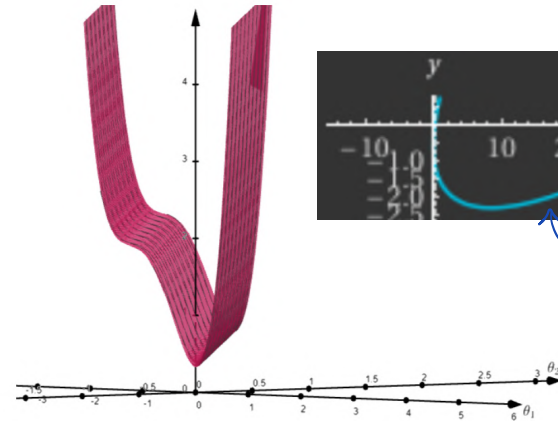
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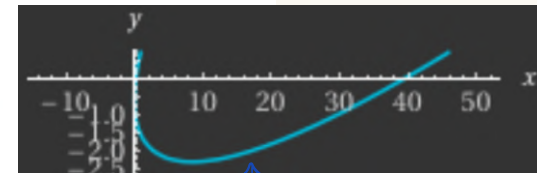
$$x = -\frac{1}{5}$$



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$$\begin{aligned} & \mathcal{M} \\ & x^2 - 10xy + 25y^2 \\ & -39x + 26y = 0 \end{aligned}$$

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Fiber-Dimension Theorem

Let $\varphi: X \rightarrow \mathbb{R}^n$ morphism between irreducible varieties.

$\Rightarrow Y := \overline{\varphi(X)}$ ^{Zariski closure} is irreducible

Thm.: There is a subvariety $\Delta \subsetneq X$ such that for all $x \in X \setminus \Delta$,
 $\dim X = \dim Y + \dim \varphi'(x)$.

Does this ring a bell from linear algebra?

Some known parameter symmetries

[Shahverdi, Marchetti, K. 2025]

$$\Theta \xrightarrow{\varphi} \mathcal{M}$$

Finkel, Rodriguez, Wu, Yahl 2024
Ulevich, Dérand, Bossi, Clavel 2025

MLPs: $\sigma(x)$ = generic polynomial of large degree: $\bar{\varphi}'(\varphi(\theta))$ finite generically
(almost proven: only permuting neurons)

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Attention: 1 layer = $\mathbb{R}^{d \times t} \rightarrow \mathbb{R}^{d' \times t}$
 $X \mapsto V X \gamma (X^T K^T Q X)$

Can you see some parameter symmetries?

Some known parameter symmetries

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Attention: 1 layer = $\mathbb{R}^{d \times t} \rightarrow \mathbb{R}^{d' \times t}$
 $X \mapsto V X \eta (X^T K^T Q X)$

Can you see some parameter symmetries?

↑ $\cdot G \bar{G}'$

$V \mapsto C V$ in one layer &

$V' \mapsto V' \bar{C}', Q' \mapsto Q' \bar{C}', K' \mapsto K' \bar{C}'$ in next layer

Conjecture: These are all parameter symmetries generically (when η is the standard softmax).

Some known parameter symmetries

$$\Theta \xrightarrow{\varphi} \mathcal{M}$$

Finkel, Rodriguez, Wu, Yahl 2024
Ulevich, Dérand, Bossi, Clavel 2025

[Shahverdi, Marchetti, K. 2025]

MLPs: $\sigma(x) = \text{generic polynomial of large degree}$: $\bar{\varphi}'(\varphi(\Theta))$ finite generically
(almost proven: only permuting neurons)

$\sigma(x) = \text{large degree monomial}$: $|\bar{\varphi}'(\varphi(\Theta))| = \infty$, coming from permuting & scaling neurons

$\sigma(x) = \text{sigmoid or tanh}$: $\bar{\varphi}'(\varphi(\Theta))$ generically finite, coming from permutating neurons
(and sign flips for tanh)

↑ Jefferyman 1994
Vlačič, Bölskei 2022

CNNs: $\sigma(x) = \text{generic polynomial of large degree}$: $\bar{\varphi}'(\varphi(\Theta)) = \{\Theta\}$ for generic Θ

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Conjecture: These are all parameter symmetries generically (when η is the standard softmax).

Theorem: For lightning attention ($\eta = \text{id}$), the only other generic parameter symmetry is scaling by a scalar within each layer.

Henry Marchetti
K. 2025

critical point theory & discriminants

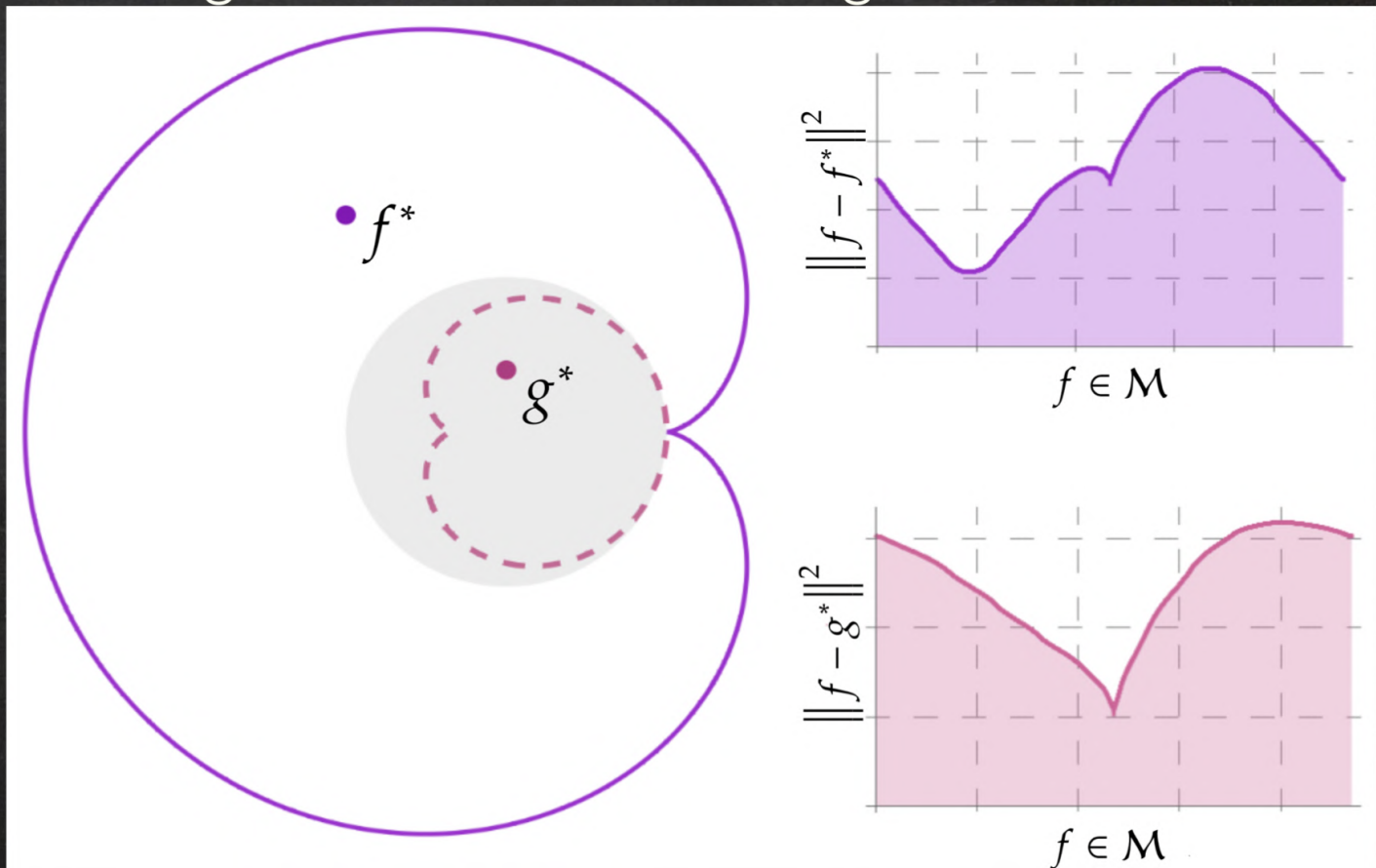
for algebraic optimization problems (e.g. mean squared error or cross entropy loss), the number of complex critical points of $\mathcal{L}_{\mathcal{D}}$ is constant for generic $\mathcal{D}$
 $\rightsquigarrow$ measures intrinsic **optimization degree**

over $\mathbb{R}$, the number or **type** (local / global minima, strict / non-strict saddle, etc.) of the critical points changes when $\mathcal{D}$ crosses an algebraic **discriminant hypersurface**

over $\mathbb{C}$: always 4
critical points

over $\mathbb{R}$: 4 or 2 critical
points

discriminant = dashed



thanks for your attention!

machine learning

algebraic geometry

sample complexity & expressivity

dimension, degree, covering number

subnetworks & implicit bias

singularities

identifiability & hidden symmetries

fibers of the parametrization

optimization & gradient descent

critical point theory, discriminants,
dynamical invariants

Position: Algebra Unveils Deep Learning An Invitation to Neuroalgebraic Geometry

Giovanni Luca Marchetti^{*1} Vahid Shahverdi^{*1} Stefano Mereta^{*1} Matthew Trager^{*2} Kathlén Kohn^{*1}

Abstract

In this position paper, we promote the study of function spaces parameterized by machine learning models through the lens of algebraic geometry. To this end, we focus on algebraic models, such as neural networks with polynomial activations, whose associated function spaces are semi-algebraic varieties. We outline a dictionary between algebro-geometric invariants of these varieties, such as dimension, degree, and singularities, and fundamental aspects of machine learning, such as sample complexity, expressivity, training dynamics, and implicit bias. Along the way, we review the literature and discuss ideas beyond the algebraic domain. This work lays the foundations of a research direction bridging algebraic geometry and deep learning, that we refer to as neuroalgebraic geometry.

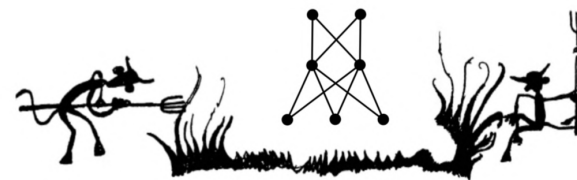


Figure 1. A neural variation of a celebrated doodle from the algebraic geometry literature (Grothendieck, 1968).

model towards an estimate of the ground-truth function. Consequently, geometric problems over neuromanifolds, such as nearest point problems, govern the training dynamics and provide insights into how neural networks learn.

Therefore, understanding the geometry of neuromanifolds offers a twofold potential. First, it serves as a powerful theoretical framework for analyzing and explaining empir-

Spotlight
Position
Paper
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thanks to

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