# The geometry of neural networks 

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Neural Networks

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Neural Networks







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Observation 1. $\Phi$ piecewise smooth $\Rightarrow \mathcal{M}_{\Phi}$ manifold with singularities


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Definition $\mathcal{M}_{\Phi}:=\left\{\Phi(w, \cdot): \mathbb{R}^{d_{x}} \rightarrow \mathbb{R}^{d_{y}} \mid w \in \mathbb{R}^{d_{w}}\right\} \subset C\left(\mathbb{R}^{d_{x}}, \mathbb{R}^{d_{y}}\right)$ is called the neuromanifold of $\phi$.

Observation 1. $\Phi$ piecewise smooth $\Rightarrow \mathcal{M}_{\Phi}$ manifold with singularities
2. $\operatorname{dim} \mathcal{M}_{\Phi} \leq d_{w}$

## Linear Networks

A linear network is defined by a $\operatorname{map} \phi: \mathbb{R}^{d_{w}} \times \mathbb{R}^{d_{x}} \longrightarrow \mathbb{R}^{d_{y}}$ of the form

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\begin{aligned}
& \Phi(w, x)=W_{h} W_{h-1} \ldots W_{1} x \\
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Note: $\mathcal{M}_{\Phi}$ is neither convex nor smooth

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## Loss Landscapes

A loss function on a neural network $\Phi: \mathbb{R}^{d_{w}} \times \mathbb{R}^{d_{x}} \longrightarrow \mathbb{R}^{d_{y}}$ is of the form

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\begin{aligned}
& L: \mathbb{R}^{d_{w}} \xrightarrow{\mu} \mathcal{M}_{\Phi} \quad \stackrel{\left.\ell\right|_{\mathcal{M}_{\Phi}}}{\longrightarrow} \mathbb{R}, \\
& w \longmapsto(w, \cdot)
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Source: Li, Hao, et al. "Visualizing the loss landscape of neural nets."
Advances in Neural Information Processing Systems. 2018.
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Observation If $\varphi \in \operatorname{Crit}\left(\left.\ell\right|_{\mathcal{M}_{\Phi}}\right)$, then $\mu^{-1}(\varphi) \subset \operatorname{Crit}(L)$.


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Recall: $\mathcal{M}_{\Phi}=\left\{M \in \mathbb{R}^{d_{h} \times d_{0}} \mid \operatorname{rk}(M) \leq r\right\}$, where $r:=\min \left\{d_{0}, d_{1}, \ldots, d_{h}\right\}$.

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Theorem Let $M \in \mathcal{M}_{\phi}$.

1. If $\operatorname{rk}(M)=r$, then $\mu^{-1}(M)$ has $2^{b}$ path-connected components

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\text { where } b:=\#\left\{i \mid 0<i<h, d_{i}=r\right\} .
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Observation If $\varphi \in \operatorname{Crit}\left(\left.\ell\right|_{\mathcal{M}_{\Phi}}\right)$, then $\mu^{-1}(\varphi) \subset \operatorname{Crit}(L)$.


## Pure \& Spurious Critical Points

A loss function on a neural network $\Phi: \mathbb{R}^{d_{w}} \times \mathbb{R}^{d_{x}} \longrightarrow \mathbb{R}^{d_{y}}$ is of the form

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Definition<br>$w^{*} \in \operatorname{Crit}(L)$ is called pure if $\mu\left(w^{*}\right) \in \operatorname{Crit}\left(\left.\ell\right|_{\mathcal{M}_{\Phi}}\right)$ and $\mu\left(w^{*}\right) \notin \operatorname{Sing} \mathcal{M}_{\Phi}$.

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Proposition If the differential $D_{w^{*}} \mu$ at $w^{*} \in \operatorname{Crit}(L)$ has maximal rank (i.e., $\left.\operatorname{rk}\left(D_{w^{*}} \mu\right)=\operatorname{dim} \mathcal{M}_{\Phi}\right)$, then $w^{*}$ is pure,

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Fixed data matrices $X \in \mathbb{R}^{d_{0} \times s}$ and $Y \in \mathbb{R}^{d_{h} \times s}$ define a quadratic loss

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Minimizing $\ell_{X, Y}$ on the determinantal variety $\mathcal{M}_{\Phi}=\{M \mid \operatorname{rk}(M) \leq r\}$ is equivalent to minimizing the Euclidean distance of $Y X^{\top}$ to $\mathcal{M}_{\phi}$.

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Let $\mathcal{Z} \subset \mathbb{C}^{N}$ be an algebraic variety.
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Equivalently: $\delta^{\text {gen }}$ is the ED degree of $\mathcal{Z}$ under the perturbed Euclidean distance $\|f(\cdot)\|_{2} . \quad X \mid-X\| \|$

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\delta\left(\mathcal{M}_{1}\right)=\min \{m, n\}
$$

## Take Away

- neuromanifolds
- pure \& spurious critical points vs. bad minima
- for linear networks with smooth convex losses:

|  | quadratic loss | other loss |
| ---: | :---: | :---: |
| filling | no bad min. | no bad min. |
| non-filling | no bad min. | bad min. |$\leftarrow$| convex optimization |
| :---: |
| on vector space |

##  <br> special embedding of <br> determinantal varieties

- future extensions to
$\diamond$ networks with polynomial activation functions or
$\diamond$ ReLU networks (using semi-algebraic sets)

