

# Point-Line Minimal Problems for 3 Cameras with Partial Visibility

Kathlén Kohn

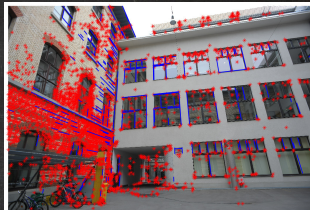
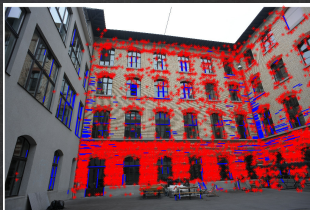
KTH Stockholm

joint work with Timothy Duff (Georgia Tech),  
Anton Leykin (Georgia Tech) & Tomas Pajdla (CTU in Prague)

Reconstruct 3D scenes and camera poses  
from 2D images

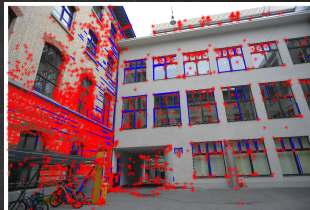
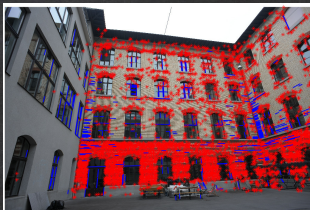
# Reconstruct 3D scenes and camera poses from 2D images

- ◆ Step 1: Identify common points and lines on given images



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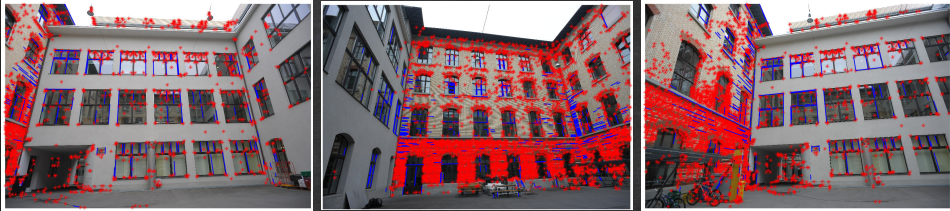
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- ◆ Step 2: Reconstruct coordinates of 3D points and lines as well as camera poses

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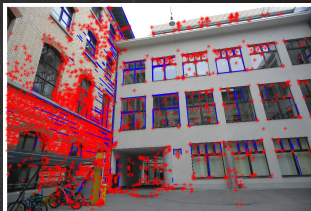
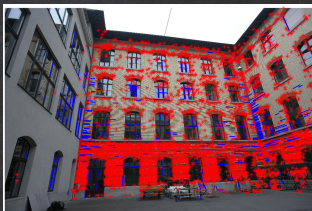


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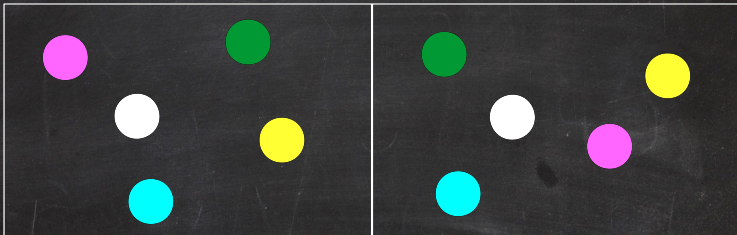


- ◆ Step 2: Reconstruct coordinates of 3D points and lines as well as camera poses

We use calibrated perspective cameras:  
each such camera is represented by a matrix  
 $[R \mid t]$ , where  $R \in \text{SO}(3)$  and  $t \in \mathbb{R}^3$

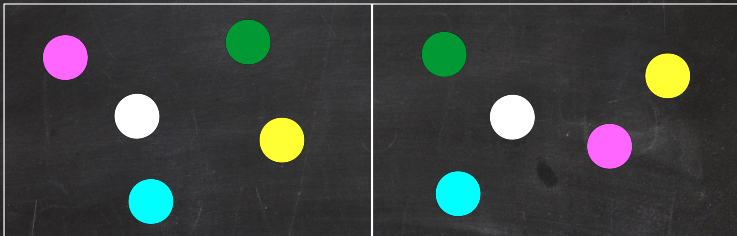
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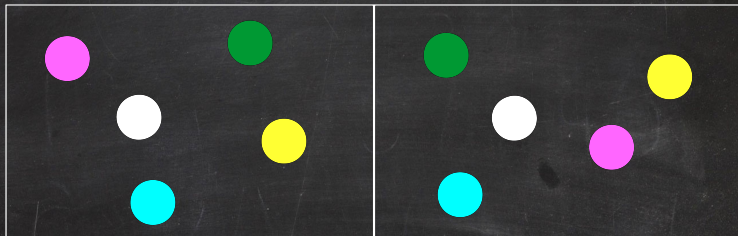
**This problem has 20 solutions over  $\mathbb{C}$ .**

(Given 2 images, a solution is 5 points in 3D and 2 camera poses.)



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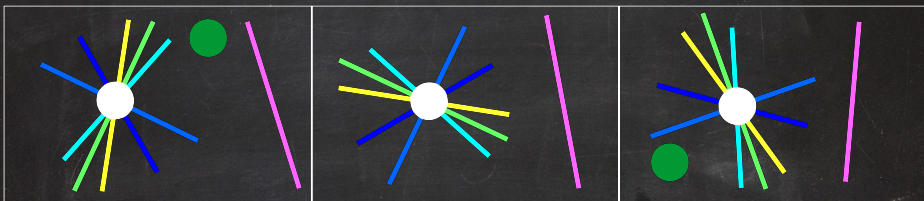
(Given 2 images, a solution is 5 points in 3D and 2 camera poses.)

**$\Rightarrow$  The 5-Point-Problem is a minimal problem!**

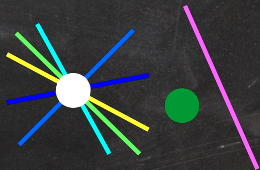
# Another minimal problem

with partial visibility

- ◆ Given: 3 images like this:



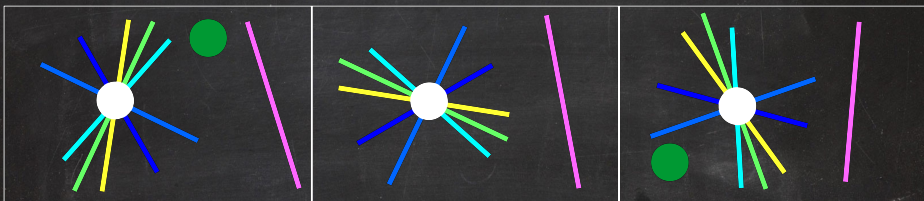
- ◆ Recover: 3 camera poses and  
3D coordinates of 2 points and 6 lines  
with the incidences:



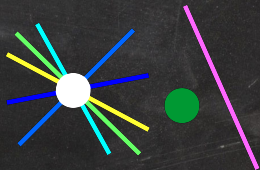
# Another minimal problem

with partial visibility

- ◆ Given: 3 images like this:



- ◆ Recover: 3 camera poses and 3D coordinates of 2 points and 6 lines with the incidences:



**This problem has 240 solutions over  $\mathbb{C}$ .**

(solution = 3 camera poses and 3D coordinates of points and lines)

⇒ It is a **minimal** problem!

# Minimal Problems

A **Point-Line-Problem (PLP)** consists of

- ◆ a number  $m$  of cameras,
- ◆ a number  $p$  of points,
- ◆ a number  $\ell$  of lines,
- ◆ a set  $\mathcal{I}$  of incidences between points and lines,
- ◆ for each camera  $c \in \{1, \dots, m\}$ , sets  $\mathcal{P}_c$  &  $\mathcal{L}_c$  of observed points & lines.

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## Definition

A PLP is **minimal** if, given  $m$  generic 2D-images, where the  $c$ -th image consists of the points and lines in  $\mathcal{P}_c$  and  $\mathcal{L}_c$  satisfying the incidences  $\mathcal{I}$ , it has a positive and finite number of solutions over  $\mathbb{C}$ .

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(solution =  $m$  camera poses and 3D coordinates of  $p$  points and  $\ell$  lines satisfying the incidences  $\mathcal{I}$ )

Can we list **all** minimal PLPs?  
How many solutions do they have?

# 30 Minimal PLPs with Complete Visibility

# views	6	5	5	5	4	4	4	4	4	4
Configuration										
# solutions	$\approx 10^6$	11296	26240	11008	3040	4512	1728	32	544	544

# views	3	3	3	3	3	3	3	3	3	3
Configuration										
# solutions	360	552	480	264	432	328	480	240	64	216

# views	3	3	3	3	3	3	3	2	2	2
Configuration										
# solutions	312	224	40	144	144	144	64	20	16	12

# What about Partial Visibility?

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1. Minimal PLPs with complete visibility have at most 6 cameras.  
**Minimal PLPs with partial visibility exist for arbitrarily many cameras!**
2. Even for a fixed number of cameras, minimal PLPs with partial visibility are much **harder to classify** than those with complete visibility!



# Assumptions

1.  $m = 3$  cameras
- 2.
- 3.
- 4.

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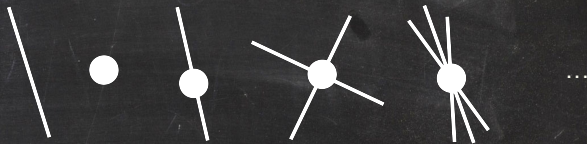
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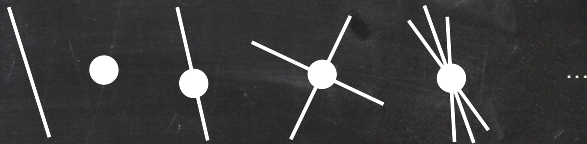
ingrediencies /  
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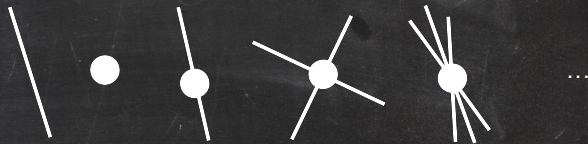
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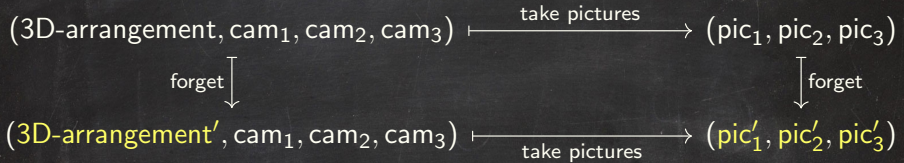


We call a PLP satisfying these assumptions a **PL1P in 3 views**.

There are **infinitely** many **minimal** PL1Ps in 3 views!!

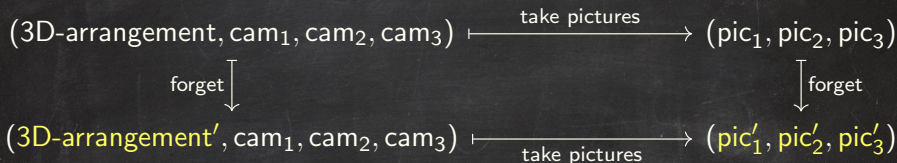
# Reduced PL1Ps

From a PL1P  $\Pi$  one can obtain a new PL1P  $\Pi'$  by forgetting some points and lines (both in 3D-space and in the camera views).



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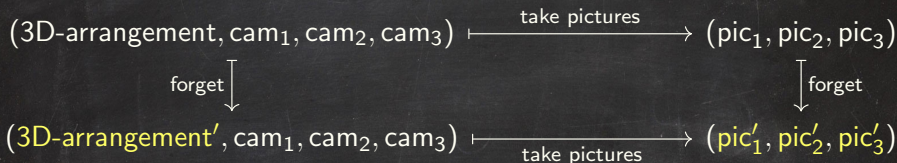
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We say that  $\Pi$  is **reducible** to  $\Pi'$  if

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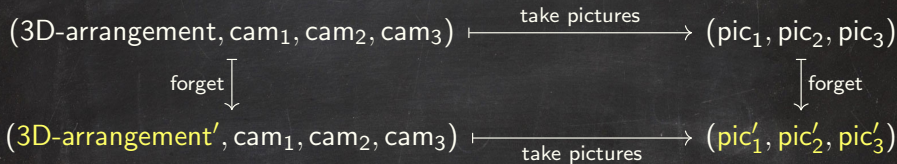
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2. for each forgotten point, at most one of its pins is kept, and
3. for generic pictures  $(\text{pic}_1, \text{pic}_2, \text{pic}_3)$ ,  
a generic solution of  $\Pi'$  on input  $(\text{pic}'_1, \text{pic}'_2, \text{pic}'_3)$   
can be lifted to a solution of  $\Pi$  on input  $(\text{pic}_1, \text{pic}_2, \text{pic}_3)$ .



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## Proposition

If a PL1P is reducible to another PL1P,  
then both have the same number of solutions (over  $\mathbb{C}$ ).

# Counting Reduced Minimal PL1Ps in 3 views

How do they look?

## Theorem

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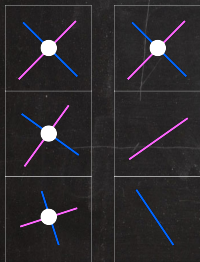
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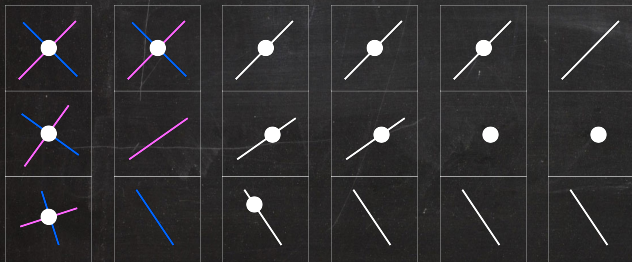
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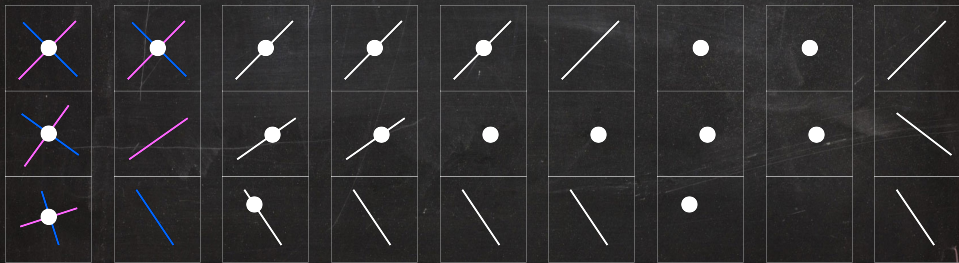
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Degrees of Freedom

3D

2D





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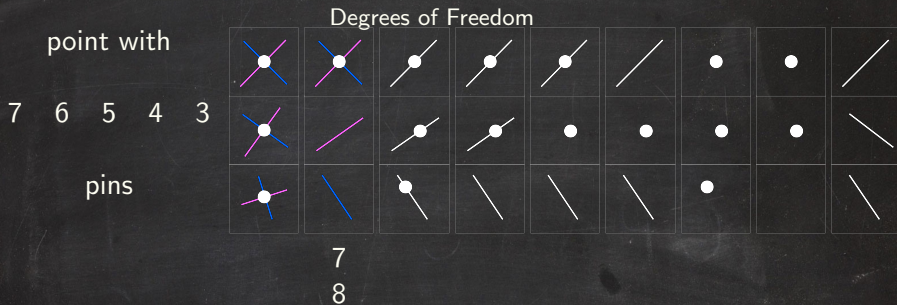
$$2 + 1 + 1$$

$$+ 2$$

$$+ 2$$

$$= 8$$

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						Degrees of Freedom							
point with													
7	6	5	4	3									
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<b>3D</b>	17	15	13	11	9	7	7	5	5	5	5	3	3
<b>2D</b>	27	24	21	18	15	12	8	9	8	7	6	6	4

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
















**Lemma:**

A minimal PL1P in 3 views satisfies:

$$\begin{array}{ccc} \text{degrees of freedom} & + & \text{camera parameters} \\ \text{in 3D} & & \end{array} = \begin{array}{ccc} \text{degrees of freedom} & & \\ & & \text{in 2D} \end{array}$$



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<b>#</b>	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	$x_6$	$x_7$	$x_8$	$x_9$	$x_{10}$	$x_{11}$	$x_{12}$	$x_{13}$	$x_{14}$

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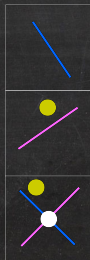
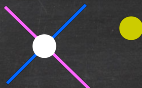
$$\begin{array}{lcl} 17x_1 + 15x_2 + 13x_3 + 11x_4 + 9x_5 & + 11 & = 27x_1 + 24x_2 + 21x_3 + 18x_4 + 15x_5 \\ + 7x_6 + 7x_7 + 5x_8 + 5x_9 + 5x_{10} & & + 12x_6 + 8x_7 + 9x_8 + 8x_9 + 7x_{10} \\ + 5x_{11} + 3x_{12} + 3x_{13} + 4x_{14} & & + 6x_{11} + 6x_{12} + 4x_{13} + 6x_{14} \end{array}$$

# Permuting single local features...

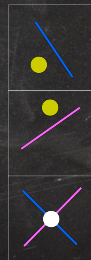
... in the 3 views changes the PL1P!

**Example:**

3D



$\neq$

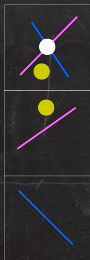
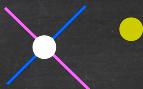


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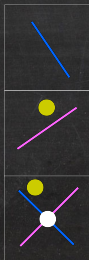
... in the 3 views changes the PL1P!

**Example:**

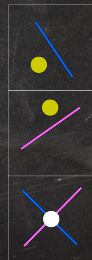
3D



=



≠



But relabeling the views does not change the PL1P.

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point with														
7	6	5	4	3										
pins														
<b>3D</b>	17	15	13	11	9	7	7	5	5	5	5	3	3	4
<b>2D</b>	27	24	21	18	15	12	8	9	8	7	6	6	4	6
<b>#</b>	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	$x_6$	$x_7$	$x_8$	$x_9$	$x_{10}$	$x_{11}$	$x_{12}$	$x_{13}$	$x_{14}$

$$\begin{aligned}
 &17x_1 + 15x_2 + 13x_3 + 11x_4 + 9x_5 + 7x_6 \\
 &\quad + 7x_7 + 5x_8 + 5x_9 + 5x_{10} \\
 &\quad + 5x_{11} + 3x_{12} + 3x_{13} + 4x_{14}
 \end{aligned}$$

+11=

$$\begin{aligned}
 &27x_1 + 24x_2 + 21x_3 + 18x_4 + 15x_5 + 12x_6 \\
 &\quad + 8x_7 + 9x_8 + 8x_9 + 7x_{10} \\
 &\quad + 6x_{11} + 6x_{12} + 4x_{13} + 6x_{14}
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<b>perm</b>	1	1	1	1	1	1		1				1		1

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 &\quad + 7x_7 + 5x_8 + 5x_9 + 5x_{10} \\
 &\quad + 5x_{11} + 3x_{12} + 3x_{13} + 4x_{14}
 \end{aligned}$$

$$+ 11 =$$

$$\begin{aligned}
 &27x_1 + 24x_2 + 21x_3 + 18x_4 + 15x_5 + 12x_6 \\
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 \end{aligned}$$

# Counting Reduced Minimal PL1Ps in 3 views

point with														
7	6	5	4	3										
pins														
<b>3D</b>	17	15	13	11	9	7	7	5	5	5	5	3	3	4
<b>2D</b>	27	24	21	18	15	12	8	9	8	7	6	6	4	6
<b>#</b>	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	$x_6$	$x_7$	$x_8$	$x_9$	$x_{10}$	$x_{11}$	$x_{12}$	$x_{13}$	$x_{14}$
<b>perm</b>	1	1	1	1	1	1	3	1				1	3	1

$$\begin{aligned}
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<b>2D</b>	27	24	21	18	15	12	8	9	8	7	6	6	4	6
<b>#</b>	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	$x_6$	$x_7^1, x_7^2, x_7^3$	$x_8$	$x_9$	$x_{10}$	$x_{11}$	$x_{12}$	$x_{13}^1, x_{13}^2, x_{13}^3$	$x_{14}$
<b>perm</b>	1	1	1	1	1	1	3	1				1	3	1
$17x_1 + 15x_2 + 13x_3 + 11x_4 + 9x_5 + 7x_6$ $+ 7x_7 + 5x_8 + 5x_9 + 5x_{10}$ $+ 5x_{11} + 3x_{12} + 3x_{13} + 4x_{14}$								+ 11 =		$27x_1 + 24x_2 + 21x_3 + 18x_4 + 15x_5 + 12x_6$ $+ 8x_7 + 9x_8 + 8x_9 + 7x_{10}$ $+ 6x_{11} + 6x_{12} + 4x_{13} + 6x_{14}$				

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<b>#</b>	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	$x_6$	$x_7^1, x_7^2, x_7^3$	$x_8$	$x_9^1, x_9^2, x_9^3$	$x_{10}^1 \dots x_{10}^6$	$x_{11}^1, x_{11}^2, x_{11}^3$	$x_{12}$	$x_{13}^1, x_{13}^2, x_{13}^3$	$x_{14}$
<b>perm</b>	1	1	1	1	1	1	3	1	3	6	3	1	3	1
$17x_1+15x_2+13x_3+11x_4+9x_5+7x_6$								+11=	$27x_1+24x_2+21x_3+18x_4+15x_5+12x_6$					
$+7x_7+5x_8+5x_9+5x_{10}$									$+8x_7+9x_8+8x_9+7x_{10}$					
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#	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	$x_6$	$x_7^1, x_7^2, x_7^3$	$x_8$	$x_9^1, x_9^2, x_9^3$	$x_{10}^1 \dots x_{10}^6$	$x_{11}^1, x_{11}^2, x_{11}^3$	$x_{12}$	$x_{13}^1, x_{13}^2, x_{13}^3$	$x_{14}$
perm	1	1	1	1	1	1	3	1	3	6	3	1	3	1

$$17x_1 + 15x_2 + 13x_3 + 11x_4 + 9x_5 + 7x_6$$

$$+ 11 =$$

$$27x_1 + 24x_2 + 21x_3 + 18x_4 + 15x_5 + 12x_6$$

$$+ 7(x_7^1 + x_7^2 + x_7^3) + 5x_8 + 5(x_9^1 + x_9^2 + x_9^3) + 5(x_{10}^1 + \dots + x_{10}^6)$$

$$+ 8(x_7^1 + x_7^2 + x_7^3) + 9x_8 + 8(x_9^1 + x_9^2 + x_9^3) + 7(x_{10}^1 + \dots + x_{10}^6)$$

$$+ 5(x_{11}^1 + x_{11}^2 + x_{11}^3) + 3x_{12} + 3(x_{13}^1 + x_{13}^2 + x_{13}^3) + 4x_{14}$$

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<b>2D</b>	27	24	21	18	15	12	8	9	8	7	6	6	4	6
<b>#</b>	$x_1$	$x_2$	$x_3$	$x_4$	$x_5$	$x_6$	$x_7^1, x_7^2, x_7^3$	$x_8$	$x_9^1, x_9^2, x_9^3$	$x_{10}^1, x_{10}^2, x_{10}^3$	$x_{11}^1, x_{11}^2, x_{11}^3$	$x_{12}$	$x_{13}^1, x_{13}^2, x_{13}^3$	$x_{14}$
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 &+ 5(x_{11}^1 + x_{11}^2 + x_{11}^3) + 3x_{12} + 3(x_{13}^1 + x_{13}^2 + x_{13}^3) + 4x_{14} + 6(x_{11}^1 + x_{11}^2 + x_{11}^3) + 6x_{12} + 4(x_{13}^1 + x_{13}^2 + x_{13}^3) + 6x_{14}
 \end{aligned}$$

Every reduced minimal PL1Ps in 3 views yields a non-negative integer solution of this equation!

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2D	27	24	21	18	15	12	8	9	8	7	6	6	4	6
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perm	1	1	1	1	1	1	3	1	3	6	3	1	3	1

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Which solutions are minimal reduced PL1Ps? XIV - XVII

# Counting Reduced Minimal PL1Ps in 3 views

Every reduced minimal PL1Ps in 3 views yields a non-negative integer solution of

$$\begin{aligned} 17x_1 + 15x_2 + 13x_3 + 11x_4 + 9x_5 + 7x_6 &+ 11 = 27x_1 + 24x_2 + 21x_3 + 18x_4 + 15x_5 + 12x_6 \\ + 7(x_7^1 + x_7^2 + x_7^3) + 5x_8 + 5(x_9^1 + x_9^2 + x_9^3) + 5(x_{10}^1 + \dots + x_{10}^6) &+ 8(x_7^1 + x_7^2 + x_7^3) + 9x_8 + 8(x_9^1 + x_9^2 + x_9^3) + 7(x_{10}^1 + \dots + x_{10}^6) \\ + 5(x_{11}^1 + x_{11}^2 + x_{11}^3) + 3x_{12} + 3(x_{13}^1 + x_{13}^2 + x_{13}^3) + 4x_{14} &+ 6(x_{11}^1 + x_{11}^2 + x_{11}^3) + 6x_{12} + 4(x_{13}^1 + x_{13}^2 + x_{13}^3) + 6x_{14} \end{aligned}$$

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◆ This equation has **845161** non-negative integer solutions.

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- ◆ This equation has **845161** non-negative integer solutions.
- ◆ Some solutions correspond to PL1Ps which are the same up to relabeling the 3 views.



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- ◆ This equation has **845161** non-negative integer solutions.
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- ◆ So the 845161 solutions describe only **143494** different PL1Ps.

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 \end{aligned}$$

- ◆ This equation has **845161** non-negative integer solutions.
- ◆ Some solutions correspond to PL1Ps which are the same up to relabeling the 3 views.
- ◆ So the 845161 solutions describe only **143494** different PL1Ps.
- ◆ Which of these 143494 PL1Ps are minimal?

# Minimality Check

## Lemma

A PL1P in 3 views satisfying the integer equation on the previous slide is **minimal** if and only if the **differential** of the map

$(3\text{D-arrangement}, \text{cam}_1, \text{cam}_2, \text{cam}_3) \xrightarrow{\text{take pictures}} (\text{pic}_1, \text{pic}_2, \text{pic}_3)$   
is **surjective** at a generic point in its domain.

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It turns out that only **5707** of the 143494 PL1Ps described by the integer equation are **not minimal**.

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## Final Result

There are **137787** reduced **minimal** PL1Ps in 3 views.

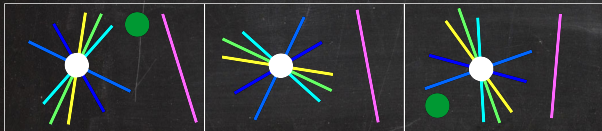


# Computing the generic number of solutions

## Ongoing work

using **homotopy continuation** and **monodromy**  
(state-of-the-art methods in  
numerical algebraic geometry)

Problem 20 in our list of 137787 minimal problems



has generically **240 solutions**

